CIRCUIT CAD AND MODELING THROUGH SPACE MAPPING

J.W. Bandler and J.E. Rayas-Sánchez

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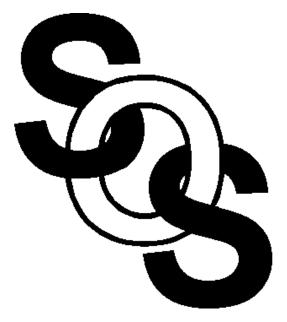
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Abstract

We review the Space Mapping (SM) approach to circuit design and discuss modeling of microwave circuits using Artificial Neural Networks (ANN). We show that SM and ANN methodologies can be combined into a powerful design SM based neuromodels decrease the cost of framework. improve generalization ability and reduce the training, complexity of the ANN topology with respect to the classical neuromodeling approach. We present and illustrate a variety of possible SM based neuromodels, including SMN, FDSMN, FSMN, FMN and FPSM. We contrast SM based neuromodeling with the classical neuromodeling approach as well as with other state-of-the-art neuromodeling techniques. The SM based neuromodeling techniques are illustrated by a microstrip line, a microstrip right angle bend and an HTS filter.

Space Mapping Optimization

(Bandler et al., 1994-)

Aggressive Space Mapping (ASM) has been applied to design examples exploiting the EM simulators

Sonnet's em

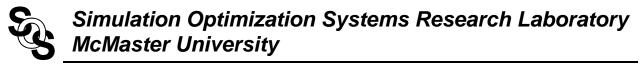
Ansoft HFSS

HP HFSS

coarse models exploit coarse grid EM models or circuittheoretic/analytical models

coarse models, decomposed into subnetworks, can even consist of a mixture of EM based subnetworks and empirical elements connected through circuit theory

new ASM algorithms TRASM (*Bakr et al., 1998*), HASM (*Bakr et al., 1999*) have been proposed



Space Mapping Based Artificial Neural Network (ANN) Modeling

(Bandler, Ismail, Rayas-Sánchez and Zhang, 1999)

Artificial Neural Networks can model high-dimensional and highly nonlinear problems (*White et al.*, 1992)

ANN models are computationally efficient and can be more accurate than empirical models

ANNs are suitable models for microwave circuit optimization and statistical design (Zaabab, Zhang and Nakhla, 1995, Gupta et al., 1996, Burrascano and Mongiardo, 1998, 1999)

ANN modeling of microwave circuits based on Space Mapping technology are exploited for the first time (*Bandler et al., 1999*)

this takes advantage of the vast set of empirical models already available

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Novel Applications of Space Mapping Technology (*Bandler et al.*, 1999)

we illustrate several new techniques to generate SM based neuromodels

Space Mapped Neuromodeling (SMN)

Frequency-Dependent Space Mapped Neuromodeling (FDSMN)

Frequency Space Mapped Neuromodeling (FSMN)

Frequency Mapped Neuromodeling (FMN)

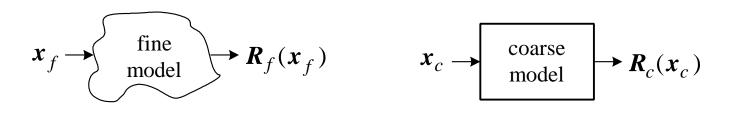
Frequency Partial-Space Mapped Neuromodeling (FPSMN)

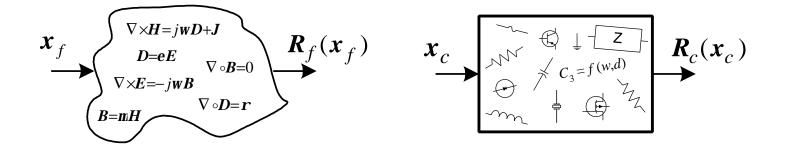
these techniques

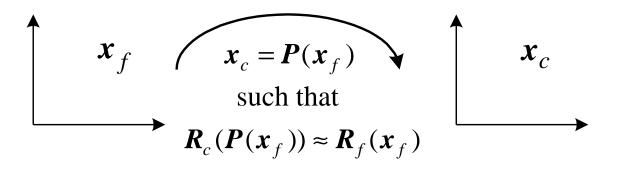
exploit the vast set of empirical models already available decrease the fine model evaluations needed for training improve generalization ability reduce complexity of the ANN topology w.r.t. the classical neuromodeling approach



The Aim of Space Mapping



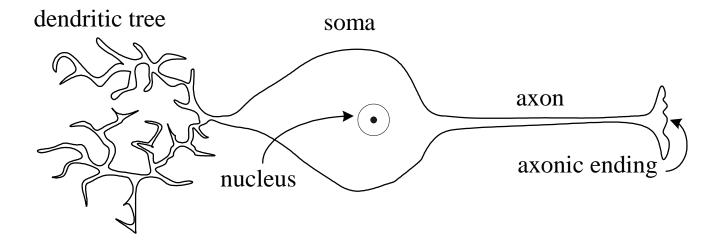




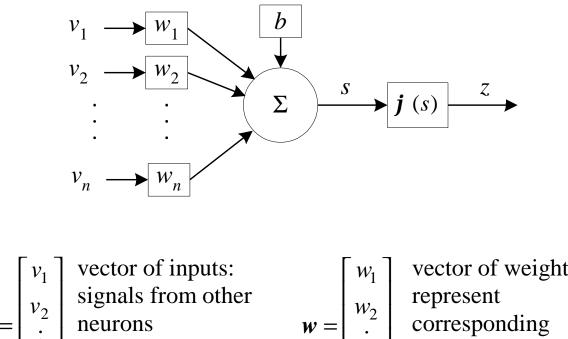


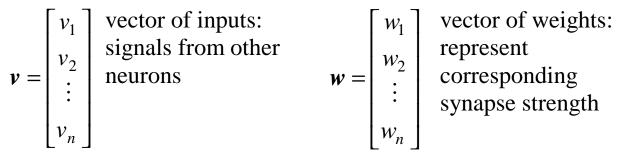
Biological Neuron

(Kartalopoulos, 1996)



Basic Model of a Neuron





b is the bias or offset term $s = b + v^T w$ is the activation signal $z = \mathbf{j}(s)$ is the output signal

if a sigmoid activation function is used

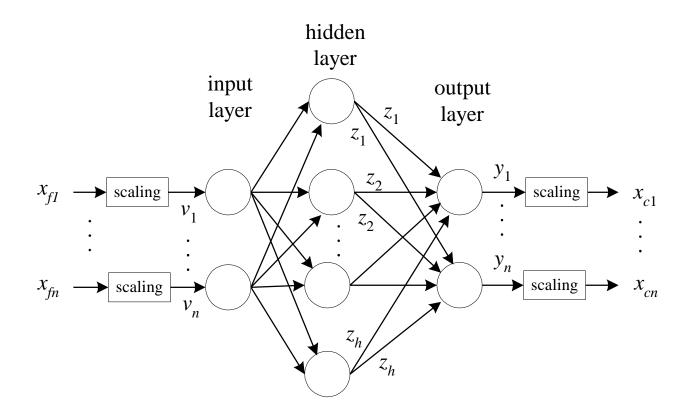
$$z = \boldsymbol{j}(s) = \frac{1}{1 + e^{-s}}$$



Neural Space Mapping

$$x_f \longrightarrow P(x_f) \longrightarrow x_c \qquad x_f \longrightarrow ANN \longrightarrow x_c$$

using a three layer perceptron (3LP)



Three Layer Perceptron (3LP)

 $\boldsymbol{x}_{f} = \begin{bmatrix} x_{f1} & x_{f2} & \cdots & x_{fn} \end{bmatrix}^{T} \text{ are } n \text{ input physical parameters}$ $\boldsymbol{v} = \begin{bmatrix} v_{1} & v_{2} & \cdots & v_{n} \end{bmatrix}^{T} \text{ are input signals after scaling}$ $\boldsymbol{z} = \begin{bmatrix} z_{1} & z_{2} & \cdots & z_{h} \end{bmatrix}^{T} \text{ are signals from the } h \text{ hidden neurons}$ $\boldsymbol{y} = \begin{bmatrix} y_{1} & y_{2} & \cdots & y_{n} \end{bmatrix}^{T} \text{ are } n \text{ output signals before scaling}$ $\boldsymbol{x}_{c} = \begin{bmatrix} x_{c1} & x_{c2} & \cdots & x_{cn} \end{bmatrix}^{T} \text{ are the neuromapping outputs}$

to control the relative importance of the input parameters and define a suitable dynamic range, scaling can be used

$$v_i = -1 + \frac{2(x_{fi} - x_{fi\min})}{(x_{fi\max} - x_{fi\min})}, i = 1, 2, \dots, n$$

Three Layer Perceptron (continued)

the hidden layer signals are calculated by

$$z_i = \mathbf{j} (b_i^h + \mathbf{v}^T \mathbf{w}_i^h), \ i = 1, 2, \cdots, h$$

 w_i^h are the vectors of synaptic weights of the hidden neurons

$$\boldsymbol{w}_{i}^{h} = \begin{bmatrix} w_{i1}^{h} & w_{i2}^{h} & \cdots & w_{in}^{h} \end{bmatrix}^{T}, \quad i = 1, 2, \cdots, h$$

 \boldsymbol{b}^h is the vector of bias elements for the hidden neurons

$$\boldsymbol{b}^{h} = \begin{bmatrix} b_{1}^{h} & b_{2}^{h} & \cdots & b_{h}^{h} \end{bmatrix}^{T}$$

the output layer signals are given by

$$y_i = b_i^o + z^T w_i^o, i = 1, 2, \cdots, n$$

 w_i^o are the vectors of synaptic weights of the output neurons

$$\boldsymbol{w}_{i}^{o} = \begin{bmatrix} w_{i1}^{o} & w_{i2}^{o} & \cdots & w_{ih}^{o} \end{bmatrix}^{T}, \quad i = 1, 2, \cdots, n$$

 \boldsymbol{b}^{o} is the vector of bias elements for the output neurons

$$\boldsymbol{b}^{o} = \begin{bmatrix} b_{1}^{o} & b_{2}^{o} & \cdots & b_{n}^{o} \end{bmatrix}^{T}$$

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Three Layer Perceptron (continued)

to provide a scaling for the output signals equivalent to the one used in the input

$$x_{ci} = x_{fi\min} + \frac{1}{2}(y_i + 1)(x_{fi\max} - x_{fi\min}), i = 1, 2, \dots, n$$

all internal parameters of the ANN can be grouped as

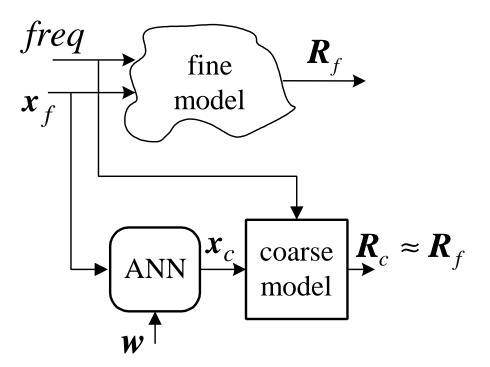
$$\boldsymbol{w} = [(\boldsymbol{b}^{h})^{T} \quad (\boldsymbol{w}_{1}^{h})^{T} \quad \dots \quad (\boldsymbol{w}_{h}^{h})^{T} \quad (\boldsymbol{b}^{o})^{T} \quad (\boldsymbol{w}_{1}^{o})^{T} \quad \dots \quad (\boldsymbol{w}_{n}^{o})^{T}]^{T}$$

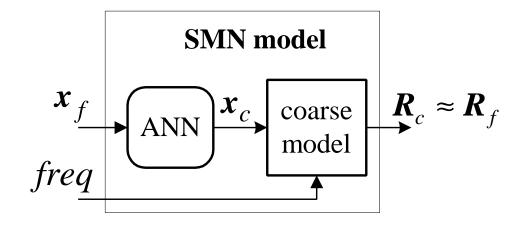
the number of optimization variables for a three-layer perceptron with n inputs, n outputs and h hidden neurons is

$$n(2h+1)+h$$



Space Mapped Neuromodeling (SMN) Concept





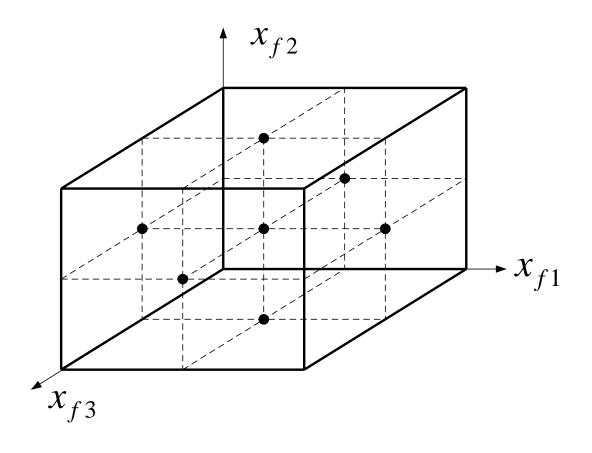


Three-dimensional Star Distribution for the Learning Base Points

(*Bandler et al.*, 1989)

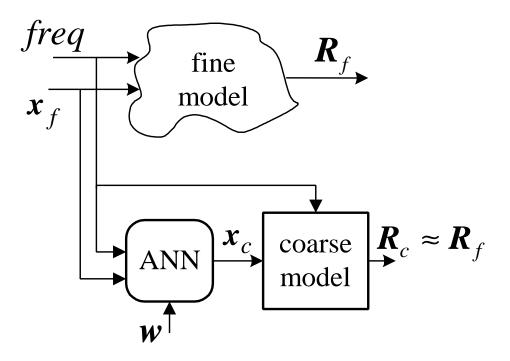
to keep a reduced set of learning data samples, we consider an n-dimensional star distribution for the base learning points

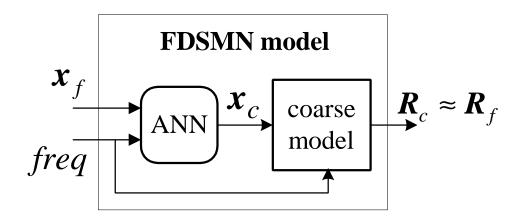
the number of learning base points for a microwave circuit with n design parameters is $B_p = 2n + 1$

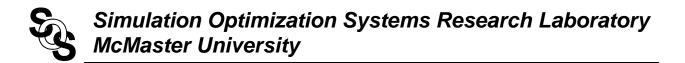


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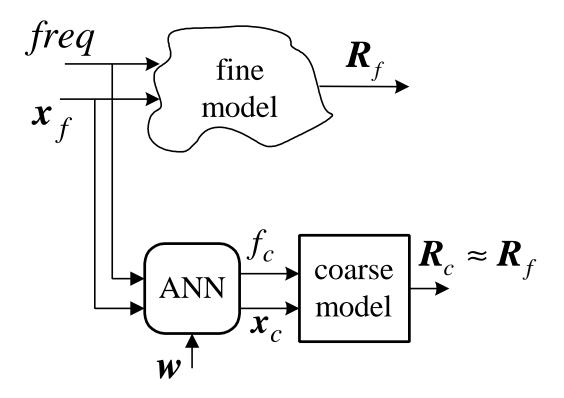
Frequency-Dependent Space Mapped Neuromodeling (FDSMN) Concept

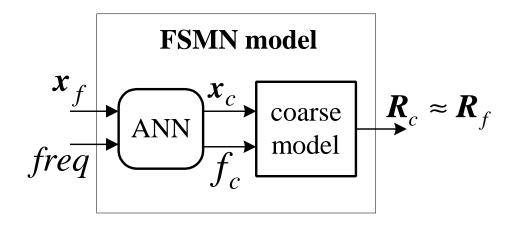






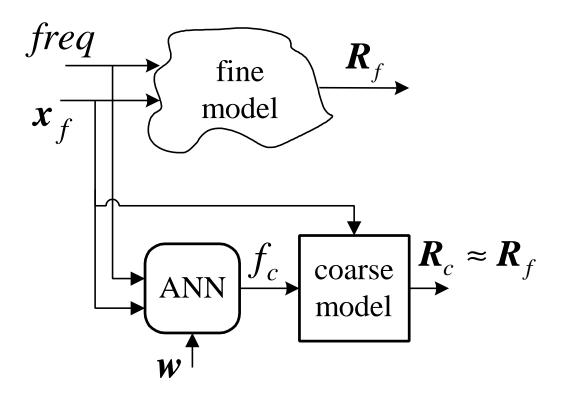
Frequency Space Mapped Neuromodeling (FSMN) Concept

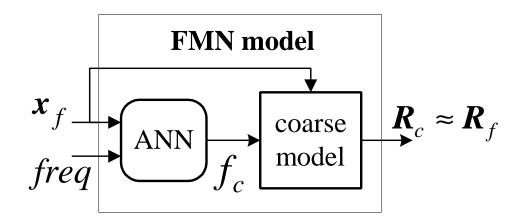






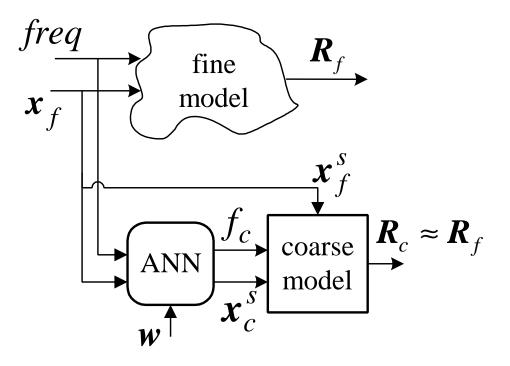
Frequency Mapped Neuromodeling (FMN) Concept

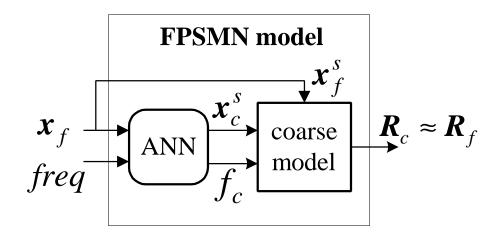






Frequency Partial-Space Mapped Neuromodeling (FPSMN) Concept





Training the ANN

the neuromapping can be found by solving the optimization problem

$$\min_{\boldsymbol{w}} \| [\boldsymbol{e}_1^T \quad \boldsymbol{e}_2^T \quad \cdots \quad \boldsymbol{e}_l^T]^T \|$$

w contains the internal parameters of the ANN (weights, bias, etc.) selected as optimization variables

l is the total number of learning samples

 e_k is the error vector given by

for SMN

$$\boldsymbol{e}_{k} = \boldsymbol{R}_{f}(\boldsymbol{x}_{f_{i}}, freq_{j}) - \boldsymbol{R}_{c}(\boldsymbol{x}_{c}, freq_{j})$$

 $\boldsymbol{x}_{c} = \boldsymbol{P}\left(\boldsymbol{x}_{f_{i}}\right)$

for FDSMN

$$\boldsymbol{e}_{k} = \boldsymbol{R}_{f}(\boldsymbol{x}_{f_{i}}, freq_{j}) - \boldsymbol{R}_{c}(\boldsymbol{x}_{c}, freq_{j})$$

$$\boldsymbol{x}_{c} = \boldsymbol{P}\left(\boldsymbol{x}_{f_{i}}, freq_{j}\right)$$

for FSMN

$$\boldsymbol{e}_k = \boldsymbol{R}_f(\boldsymbol{x}_{f_i}, freq_j) - \boldsymbol{R}_c(\boldsymbol{x}_c, f_c)$$



Training the ANN (continued)

$$\begin{bmatrix} \boldsymbol{x}_c \\ f_c \end{bmatrix} = \boldsymbol{P}\left(\boldsymbol{x}_{f_i}, freq_j\right)$$

for FMN

$$\boldsymbol{e}_{k} = \boldsymbol{R}_{f}(\boldsymbol{x}_{f_{i}}, freq_{j}) - \boldsymbol{R}_{c}(\boldsymbol{x}_{f_{i}}, f_{c})$$
$$f_{c} = P(\boldsymbol{x}_{f_{i}}, freq_{j})$$

for FPSMN

$$\boldsymbol{e}_{k} = \boldsymbol{R}_{f}(\boldsymbol{x}_{f_{i}}, freq_{j}) - \boldsymbol{R}_{c}(\boldsymbol{x}_{f_{i}}^{s}, \boldsymbol{x}_{c}^{s}, f_{c})$$

$$\begin{bmatrix} \boldsymbol{x}_{c}^{s} \\ f_{c} \end{bmatrix} = \boldsymbol{P}\left(\boldsymbol{x}_{f_{i}}, freq_{j}\right)$$

with

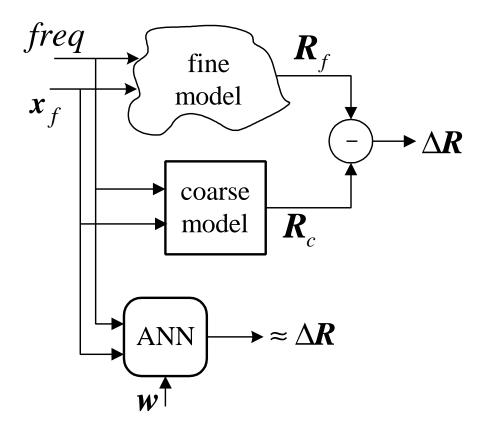
$$i = 1, \dots, B_p$$
$$j = 1, \dots, F_p$$
$$k = j + F_p (i - 1)$$



EM-ANN Neuromodeling Concept

(Gupta et al., 1996)

an interpretation using our notation

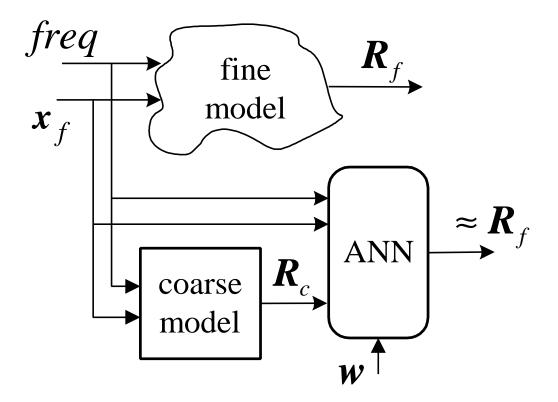


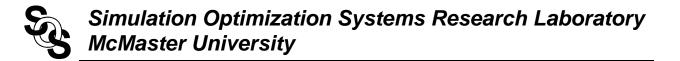


PKI Neuromodeling Concept

(Gupta et al., 1996)

an interpretation using our notation

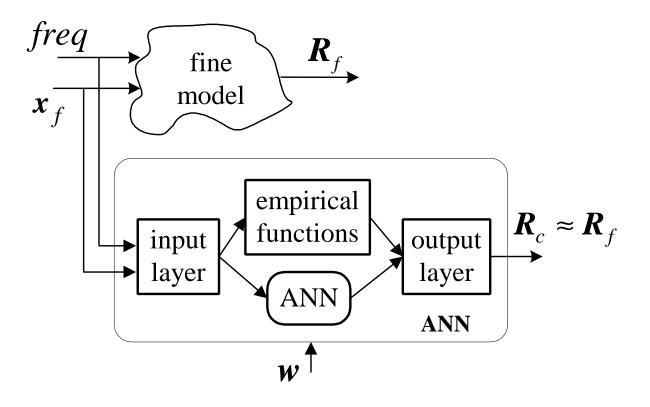




KBNN Neuromodeling Concept

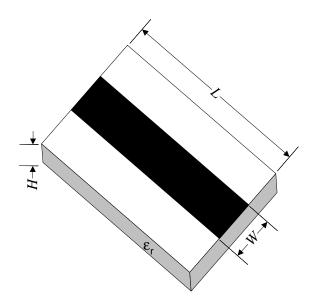
(Zhang et al., 1997)

an interpretation using our notation





Microstrip Line with High Dielectric Constant



region of interest

 $5 \text{mil} \le W \le 9 \text{mil}$ $15 \text{mil} \le H \le 25 \text{mil}$ $40 \text{mil} \le L \le 60 \text{mil}$ $20 \le \mathbf{e}_{r} \le 25$ $27 \text{GHz} \le freq \le 30 \text{GHz}.$

"coarse" model: Pozar's formulas (Pozar, 1998)

"fine" model: Sonnet's *em*TM

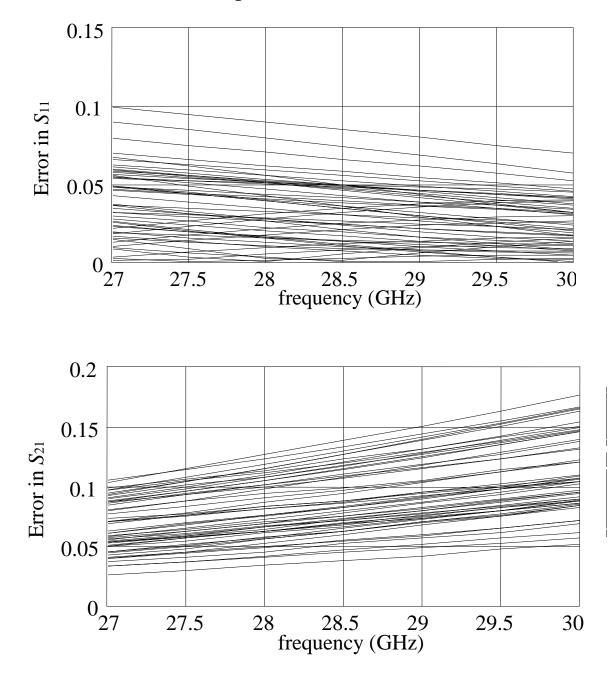
learning set: 9 base points with "star" distribution

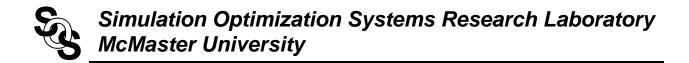
testing set: 50 random base points in the region of interest



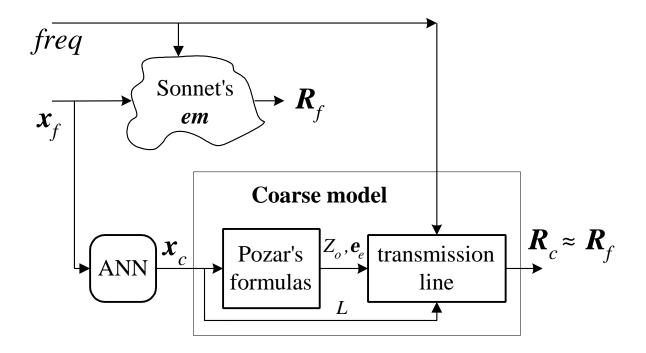
Microstrip Line Response Errors

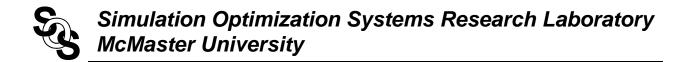
comparison before neuromodeling between em^{TM} and Pozar's model at 50 random test points





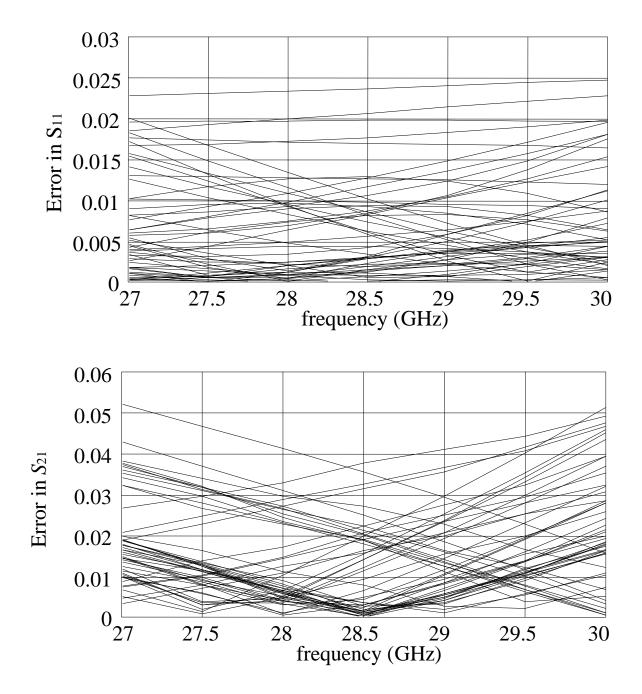
SMN Model for the Microstrip Line (3LP:4-3-4)





SMN Model Results for the Microstrip Line

comparison between em^{TM} and the SMN model





SMN Model for the Microstrip Line Implemented in OSA90

Expression ! w : Width of the flat conductor in the PCB (in mils) ! h : Thickness of the PWB laminate (in mils) ! l : Length of the flat conductors (in mils) ! epsr : Dielectric constant of the PWB laminate ! Xf[i]= [w(i) h(i) l(i) epsr(i)] i: 1;! Index for the training/test points end Model #include "mcsl_hepsr.inc"; ! SONNET'S MODEL: mcsl_hepsr @f1 @f2 0 l=(Xf[i,3]*1mil) w=(Xf[i,1]*1mil) h=(Xf[i,2]*1mil) epsr=(Xf[i,4]); ports @f1 0 @f2 0 ;! Ports 1-2 for Sonnet's model ! Neuromapping (3LP: 4-3-4) ! input scaling v1=-1+2*(Xf[i,1]-Xf1_min) / (Xf1_max - Xf1_min); v2=-1+2*(Xf[i,2]-Xf2_min) / (Xf2_max - Xf2_min); v3=-1+2*(Xf[i,3]-Xf3_min) / (Xf3_max - Xf3_min); v4=-1+2*(Xf[i,4]-Xf4_min) / (Xf4_max - Xf4_min); ! vectors of synaptic weights of the hidden neurons : wh wh1[4]: [?0.0997064? ?0.00926408? ?-0.0010517? ?0.00555616?]; wh2[4]: [?-0.0254024? ?0.100381? ?0.00506993? ?-0.0277744?]; wh3[4]: [?-0.00263021? ?0.00403475? ?0.152244? ?0.0449023?]; ! vector of bias elements for the hidden neurons : bh bh[3]: [?0.0379664? ?-0.0373888? ?0.016498?]; ! hidden layer z1 = tanh(bh[1]+v1*wh1[1]+v2*wh1[2]+v3*wh1[3]+v4*wh1[4]); $z_{2} = tanh(bh[2]+v_{1}*wh_{2}[1]+v_{2}*wh_{2}[2]+v_{3}*wh_{2}[3]+v_{4}*wh_{2}[4]);$ z3 = tanh(bh[3]+v1*wh3[1]+v2*wh3[2]+v3*wh3[3]+v4*wh3[4]);! vectors of synaptic weights of the output neurons : wo



```
wo1[3]: [?9.97323? ?8.37909e-005? ?6.37812e-006?];
wo2[3]: [?-0.000228351? ?10.0461? ?-7.25383e-005?];
wo3[3]: [?0.0112826? ?-0.0014412? ?6.85617?];
wo4[3]: [?0.00258169? ?0.000209437? ?-0.00683818?];
! vector of bias elements for the output neurons : bo
bo[4]: [?0.00394671? ?-0.00393648? ?0.0121073? ?-0.01383?];
! output layer
y1 = bo[1]+z1*wo1[1]+z2*wo1[2]+z3*wo1[3];
y_2 = bo[2]+z_1*w_2[1]+z_2*w_2[2]+z_3*w_2[3];
y_3 = bo[3]+z_1*w_3[1]+z_2*w_3[2]+z_3*w_3[3];
y4 = bo[4]+z1*w04[1]+z2*w04[2]+z3*w04[3];
! output scaling
Xc1 = Xf1_min + 0.5*(y1+1)*(Xf1_max - Xf1_min);
Xc2 = Xf2_min + 0.5*(y2+1)*(Xf2_max - Xf2_min);
Xc3 = Xf3_min + 0.5*(y3+1)*(Xf3_max - Xf3_min);
Xc4 = Xf4_min + 0.5*(y4+1)*(Xf4_max - Xf4_min);
! POZAR'S MODEL (TRANSMISSION LINE)
epse=(Xc4+1)/2+(Xc4-1)/(2 *sqrt(1+12*Xc2/Xc1));
Zo = if((Xc1/Xc2) < 1)
  (60/sqrt(epse) * log(8*Xc2/Xc1+Xc1/(4*Xc2)))
    else
  (120*pi/(sqrt(epse)*(Xc1/Xc2+1.393+0.667*log(Xc1/Xc2+1.444))));
TRL @c1 @c2 Z=Zo L=(Xc3*1mil) K=epse F=FREQ;
ports @c1 0 @c2 0 ;! Ports 3-4 for Pozar's model
CIRCUIT;
end
Sweep
AC: i: from 1 to N step 1
    FREQ: from Freq_min to Freq_max step=Freq_step
"rS11 (Sonnet)","iS11 (Sonnet)","rS21 (Sonnet)","iS21 (Sonnet)"
"rS11 (SMN)","iS11 (SMN)","rS21 (SMN)","iS21 (SMN)"
end
Specification
   AC: i: from 1 to NL step 1
         FREQ: from Freq_min to Freq_max step=Freq_step
                  "rS11 (SMN)" = "rS11 (Sonnet)"
                  "iS11 (SMN)" = "iS11 (Sonnet)"
                  "rS21 (SMN)" = "rS21 (Sonnet)"
                  "iS21 (SMN)" = "iS21 (Sonnet)"
```

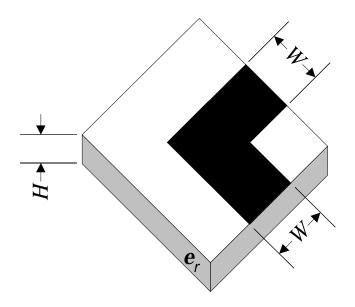


end

```
Control
Perturbation_Scale=1.0e-4;
Disable_Adjoint;
Allow_Neg_Parameters;
Optimizer=Huber;
N_iterations=100;
Display_N_digits=6;
Accuracy=1.0e-5;
Huber_threshold=0.15;
end
```



Microstrip Right Angle Bend



region of interest

 $20 \text{mil} \le W \le 30 \text{mil}$ $8 \text{mil} \le H \le 16 \text{mil}$ $8 \le \mathbf{e}_{r} \le 10$ $1 \text{GHz} \le freq \le 41 \text{GHz}$

"coarse" model: Gupta model

"fine" model: Sonnet's *em*TM

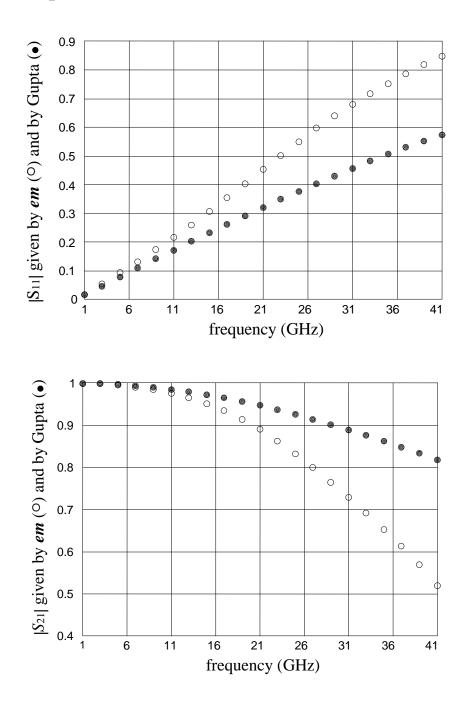
learning set: 7 base points with "star" distribution

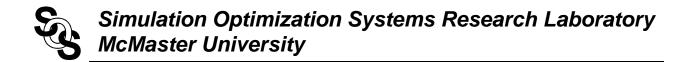
testing set: 50 random base points in the region of interest



Microstrip Right Angle Bend Responses

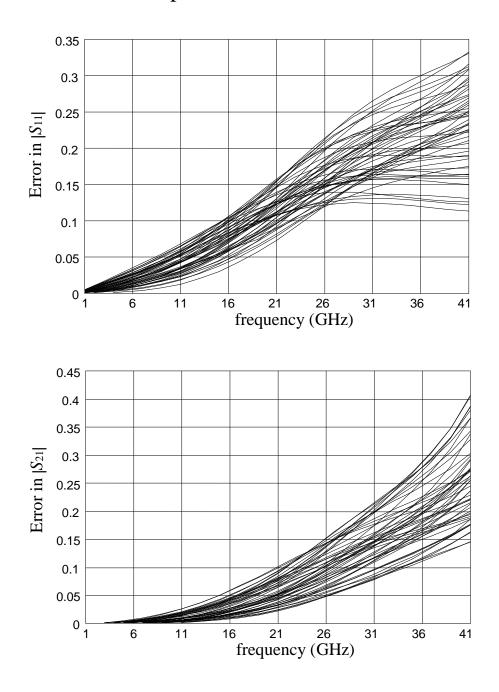
typical responses before neuromodeling em^{TM} (o), Gupta model (•)

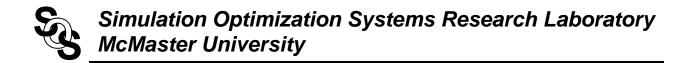




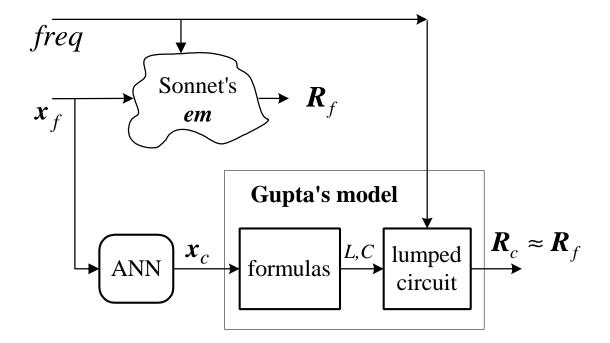
Microstrip Right Angle Bend Response Errors

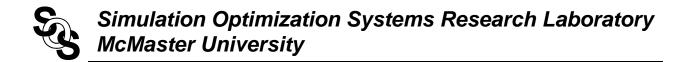
comparison before neuromodeling between em^{TM} and Gupta model at 50 random test points





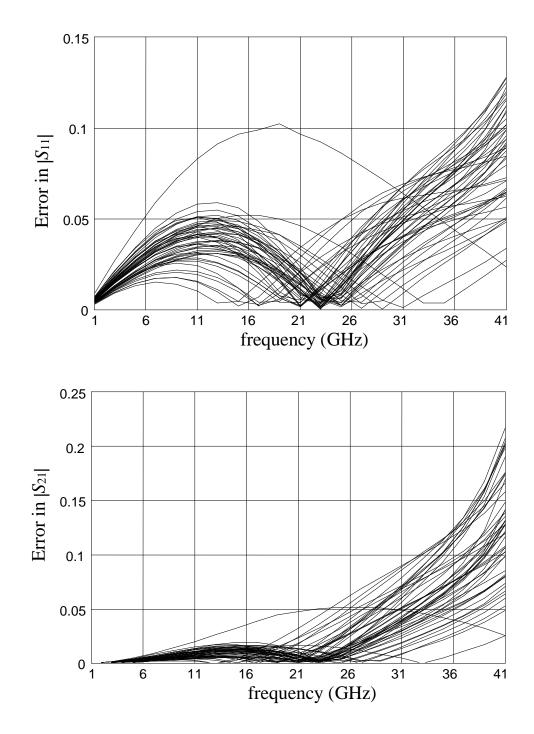
SMN Model for the Right Angle Bend (3LP:3-6-3)

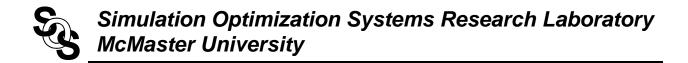




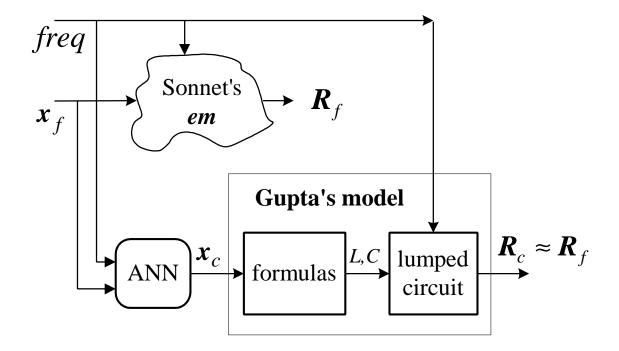
SMN Model Results for the Right Angle Bend

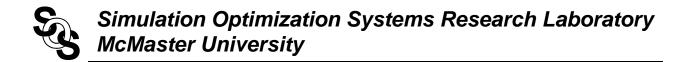
comparison between em^{TM} and the SMN model





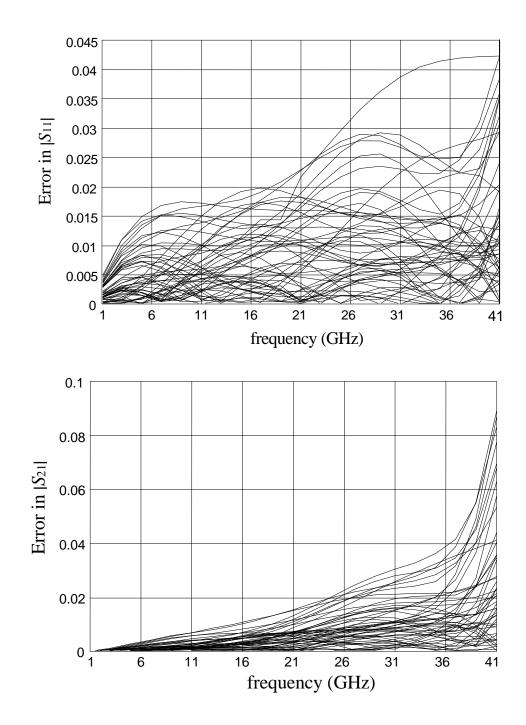
FDSMN Model for the Right Angle Bend (3LP:4-7-3)

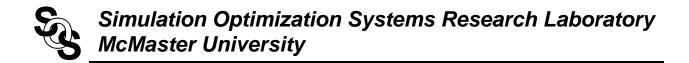




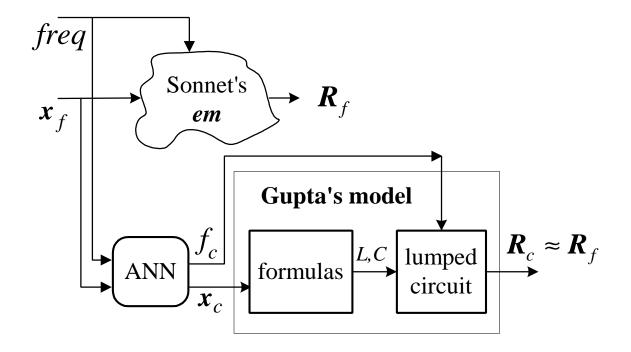
FDSMN Model Results for the Right Angle Bend

comparison between em^{TM} and the FDSMN model

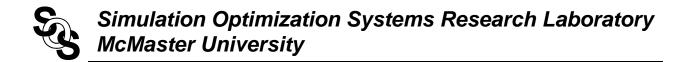




FSMN Model for the Right Angle Bend (3LP:4-8-4)

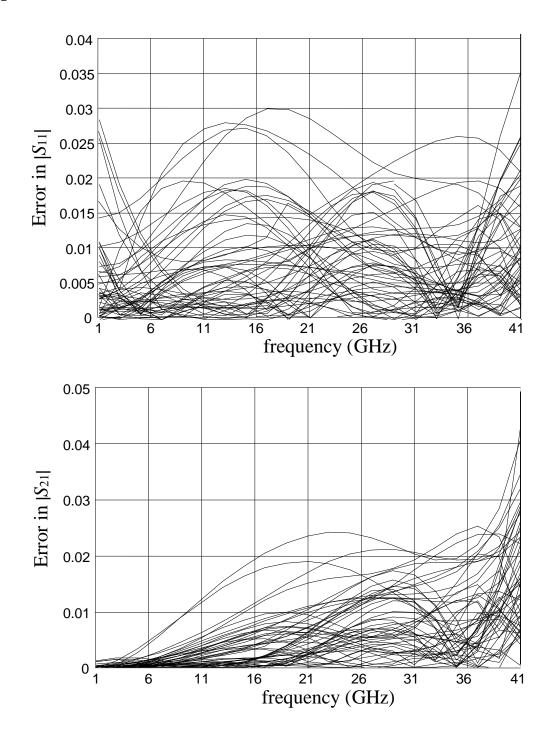


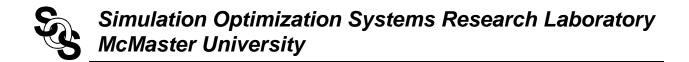
to implement the FSMN approach, an OSA90/hope[™] child program is employed to simulate the coarse model with a different frequency variable using Datapipe



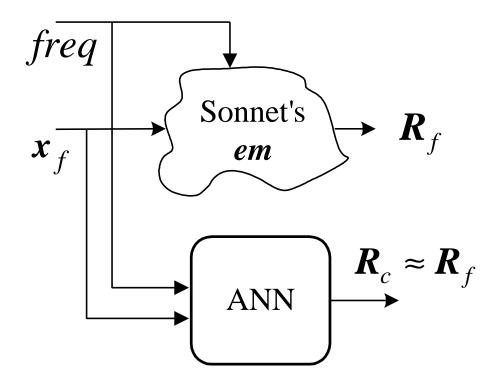
FSMN Model Results for the Right Angle Bend

comparison between em^{TM} and the FSMN model





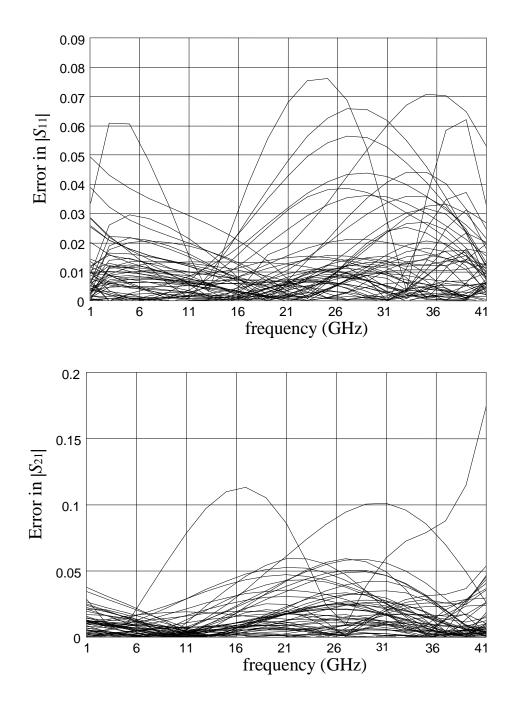
Classical Neuromodel for the Right Angle Bend (3LP:4-15-4)





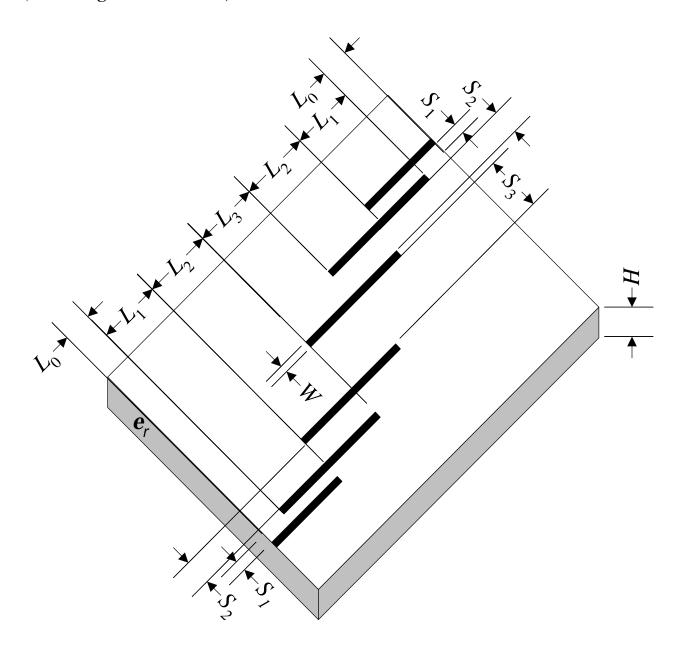
Classical Neuromodel Results for the Right Angle Bend (*Neuromodeler*, 1998)

comparison between em^{TM} and classical neuromodel





HTS Quarter-Wave Parallel Coupled-Line Microstrip Filter (Westinghouse, 1993)



SM Based Neuromodeling of the HTS Filter

region of interest

 $\begin{array}{l} 175 \, \mathrm{mil} \leq L_1 \leq 185 \, \mathrm{mil} \\ 190 \, \mathrm{mil} \leq L_2 \leq 210 \, \mathrm{mil} \\ 175 \, \mathrm{mil} \leq L_3 \leq 185 \, \mathrm{mil} \\ 18 \, \mathrm{mil} \leq S_1 \leq 22 \, \mathrm{mil} \\ 75 \, \mathrm{mil} \leq S_2 \leq 85 \, \mathrm{mil} \\ 70 \, \mathrm{mil} \leq S_3 \leq 90 \, \mathrm{mil} \\ 3.901 \, \mathrm{GHz} \leq freq \leq 4.161 \, \mathrm{GHz} \end{array}$

 $L_0 = 50 \text{mil}$ H = 20 milW = 7 mil $\boldsymbol{e}_r = 23.425$ loss tangent = 3×10⁻⁵

"coarse" model: OSA90/hopeTM empirical models

"fine" model: Sonnet's *em*TM with high resolution grid

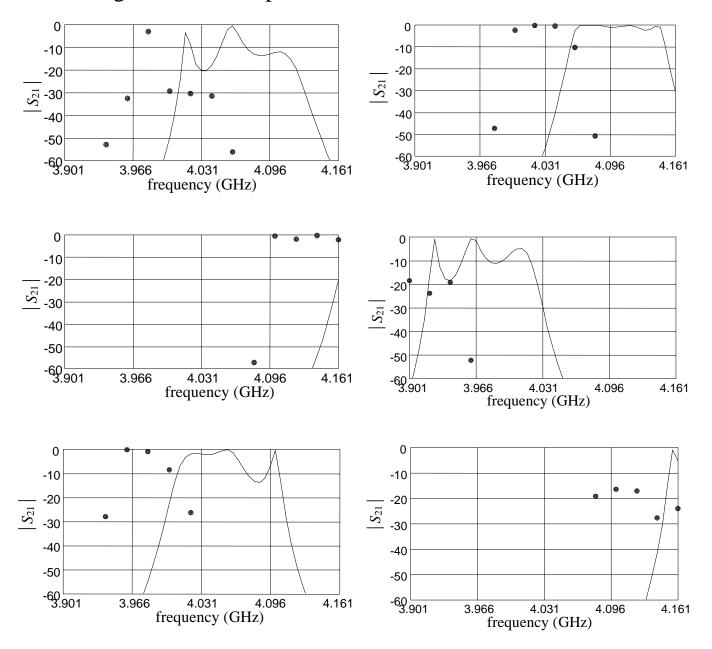
learning set: 13 base points with "star" distribution

testing set: 7 random base points in the region of interest (not seen in the learning set)



HTS Filter Responses Before Neuromodeling

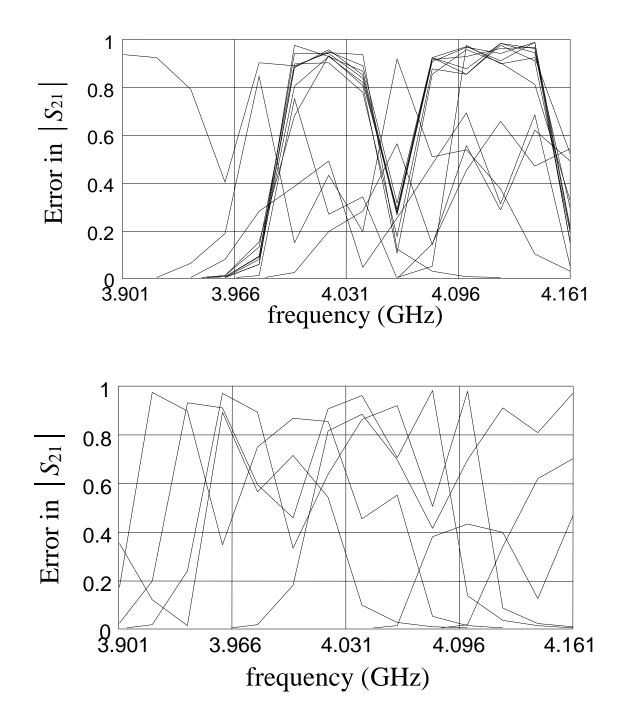
responses using em^{TM} (•) and OSA90/hopeTM (–) at three learning and three test points

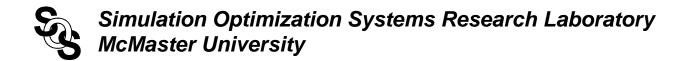


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HTS Filter Response Errors Before Neuromodeling

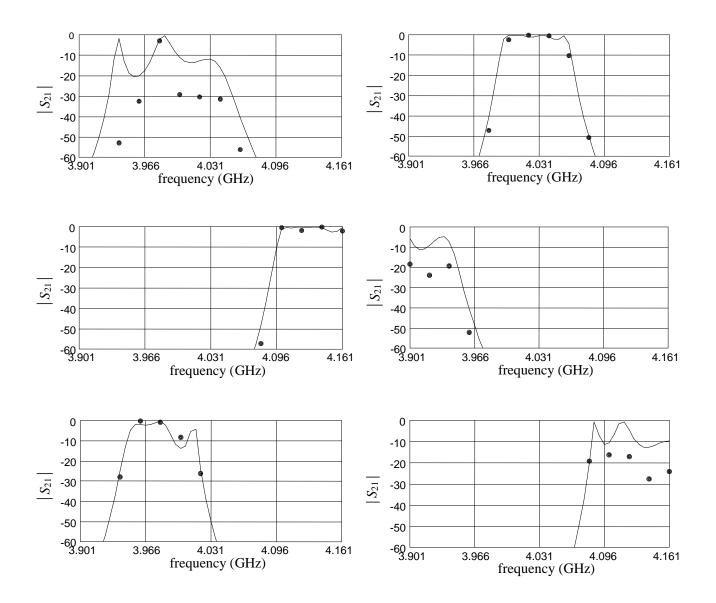
coarse model error w.r.t. em^{TM} at the learning and testing sets

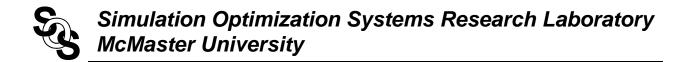




FMN Model for the HTS Filter (3LP:7-5-1)

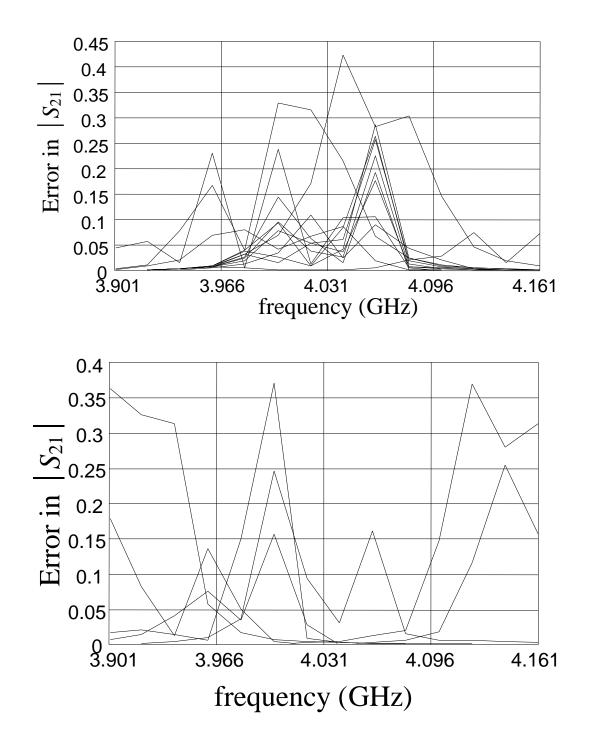
responses using em^{TM} (•) and FMN model (–) at the three learning and three testing points





FMN Model Response Errors for the HTS Filter

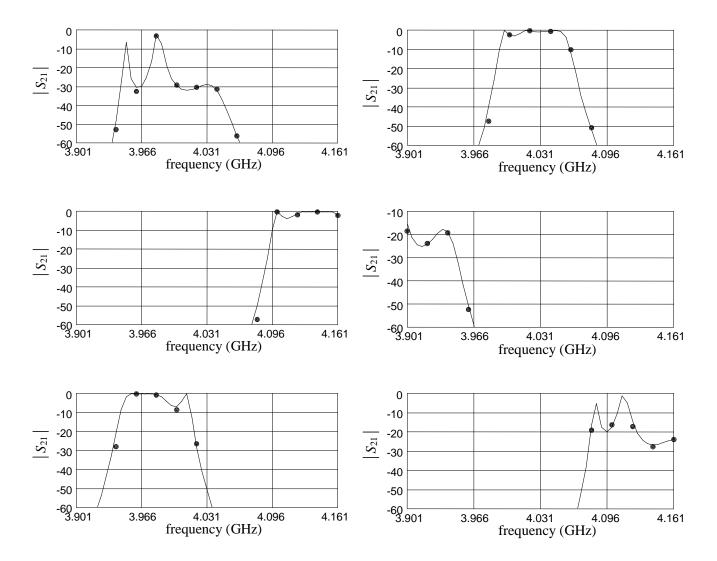
FMN model error w.r.t. em^{TM} at the learning and testing sets



FPSMN Model Responses for the HTS Filter (3LP:7-7-3)

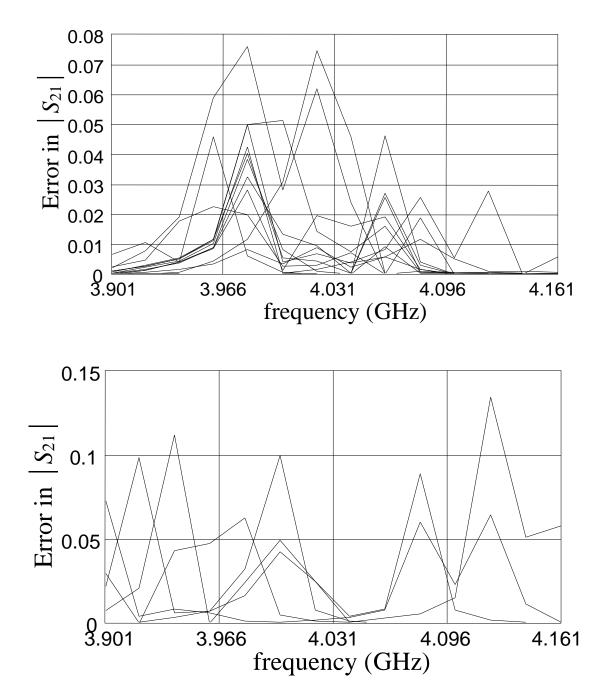
taking $x_{c}^{s} = [L_{1c} S_{1c}]^{T}$ and $x_{f}^{s} = [L_{2} L_{3} S_{2} S_{3}]^{T}$

responses using em^{TM} (•) and FPSMN model (–) at the three learning and three testing points



FPSMN Model Response Errors for the HTS Filter

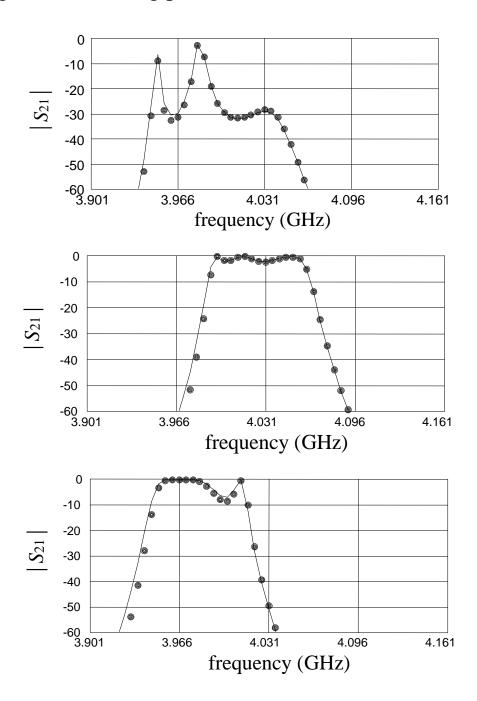
FPSMN model error w.r.t. em^{TM} at the learning and testing sets



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FPSMN Model for the HTS Filter: Fine Frequency Sweep

comparison between em^{TM} (•) and FPSMN model (–) at two learning and one testing points





Conclusions

we present novel applications of Space Mapping technology to the neuromodeling of microwave circuits

five powerful techniques to generate SM based neuromodels are illustrated: SMN, FDSMN, FSMN, FMN and FPSM

OSA90/hope[™] implementations are illustrated

frequency-sensitive neuromappings expand the usefulness of quasi-static empirical models

FMN effectively aligns frequency-shifted responses

Huber optimization efficiently trains the neuromappings, exploiting its robust characteristics for data fitting

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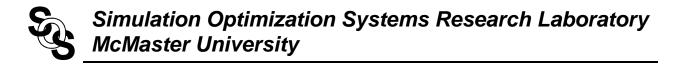
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