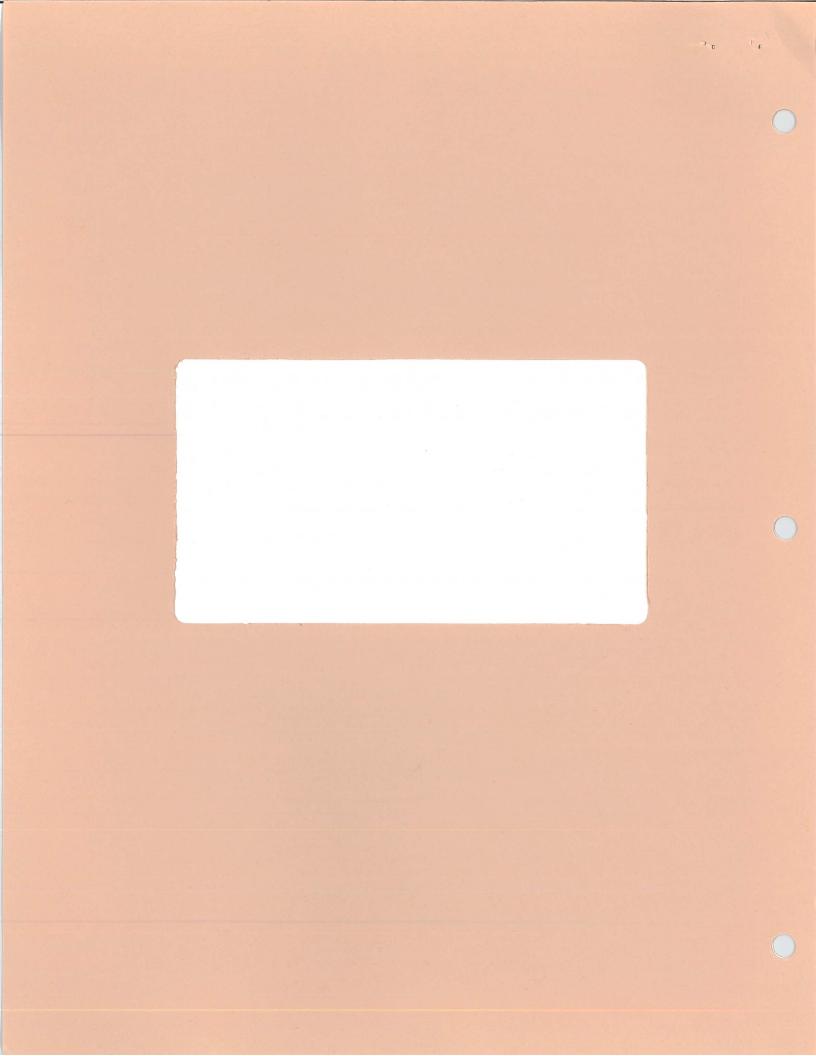


# SIMULATION OPTIMIZATION SYSTEMS Research Laboratory

## NOTES ON VECTORS, MATRICES AND SENSITIVITIES

J.W. Bandler and Q.J. Zhang SOS-86-8-R September 1986



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Matrix A

Let

$$\mathbf{A} \stackrel{\triangle}{=} \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ & \ddots & & & \\ & \ddots & \ddots & & \\ & \ddots & \ddots & & \\ & a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$

This mxn matrix has m rows and n columns.

#### Transpose of A

$$\mathbf{A}^{T} \triangleq \begin{bmatrix} a_{11} & a_{21} & \dots & a_{m1} \\ a_{12} & a_{22} & \dots & a_{m2} \\ & \ddots & & & \\ & a_{1n} & a_{2n} & \dots & a_{mn} \end{bmatrix}$$

This nxm matrix has n rows and m columns.

#### Symmetric Matrix A

A square matrix A is said to be symmetric if

$$\mathbf{A}^{\mathrm{T}} = \mathbf{A}$$

Vector a

Let

$$\mathbf{a} \stackrel{\triangle}{=} \begin{bmatrix} \mathbf{a}_1 \\ \mathbf{a}_2 \\ \vdots \\ \vdots \\ \mathbf{a}_n \end{bmatrix}$$

This n-dimensional vector has n rows and 1 column.

Transpose of a

$$\mathbf{a}^{\mathrm{T}} \stackrel{\Delta}{=} [\mathbf{a}_{1} \quad \mathbf{a}_{2} \quad \dots \quad \mathbf{a}_{n}]$$

This n-dimensional vector has 1 row and n columns.

 $\underline{Vector a'}$ 

Let

$$\mathbf{a}' \stackrel{\Delta}{=} \left[ \begin{array}{c} \mathbf{a}_1 \\ \mathbf{a}_2 \\ \vdots \\ \vdots \\ \mathbf{a}_m \end{array} \right]$$

This m-dimensional vector has m rows and 1 column.

Transpose of a'

$$\mathbf{a'}^{T} \stackrel{\Delta}{=} [\mathbf{a}_1' \quad \mathbf{a}_2' \quad \dots \quad \mathbf{a}_m']$$

This m-dimensional vector has 1 row and m columns.

Forms of A and  $A^T$ 

Partitioned forms of A and AT can be written as

$$\mathbf{A}^{\mathrm{T}} = [\mathbf{a}_{1} \quad \mathbf{a}_{2} \quad \dots \quad \mathbf{a}_{m}] = \begin{bmatrix} \mathbf{a}_{1}^{'\mathrm{T}} \\ \mathbf{a}_{2}^{'\mathrm{T}} \\ \vdots \\ \vdots \\ \mathbf{a}_{n}^{'\mathrm{T}} \end{bmatrix} = \mathbf{A}'$$

and

$$\mathbf{A} = \begin{bmatrix} \mathbf{a}_1^T \\ \mathbf{a}_2^T \\ \vdots \\ \vdots \\ \mathbf{a}_m^T \end{bmatrix} = [\mathbf{a}_1^{'} \quad \mathbf{a}_2^{'} \quad \dots \quad \mathbf{a}_n^{'}] = \mathbf{A}^{'T}$$

Here,  $\mathbf{a}_1, \mathbf{a}_2, ..., \mathbf{a}_m$  are n-dimensional, whereas  $\mathbf{a}_1', \mathbf{a}_2', ..., \mathbf{a}_n'$  are m-dimensional.

Rows of A

$$\mathbf{A} = \begin{bmatrix} \mathbf{a}_1^T \\ \mathbf{a}_2^T \\ & \\ & \\ & \\ \mathbf{a}_m^T \end{bmatrix}$$

This mxn matrix has rows which are the transposes of the column vectors

$$\mathbf{a}_{1} \triangleq \begin{bmatrix} a_{11} \\ a_{12} \\ \vdots \\ \vdots \\ a_{1n} \end{bmatrix}, \quad \mathbf{a}_{2} \triangleq \begin{bmatrix} a_{21} \\ a_{22} \\ \vdots \\ \vdots \\ \vdots \\ a_{2n} \end{bmatrix}, \quad \dots, \quad \mathbf{a}_{m} \triangleq \begin{bmatrix} a_{m1} \\ a_{m2} \\ \vdots \\ \vdots \\ \vdots \\ \vdots \\ a_{mn} \end{bmatrix}$$

#### Columns of A

$$\mathbf{A} = [\mathbf{a}_1^{'} \quad \mathbf{a}_2^{'} \quad \dots \quad \mathbf{a}_n^{'}]$$

This mxn matrix has columns

$$\mathbf{a}_{1}^{'} \triangleq \begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{m1} \end{bmatrix}, \quad \mathbf{a}_{2}^{'} \triangleq \begin{bmatrix} a_{12} \\ a_{22} \\ \vdots \\ \vdots \\ a_{m2} \end{bmatrix}, \quad \dots, \quad \mathbf{a}_{n}^{'} \triangleq \begin{bmatrix} a_{1n} \\ a_{2n} \\ \vdots \\ \vdots \\ a_{mn} \end{bmatrix}$$

Unit Vector ui

$$\mathbf{u}_{i} \stackrel{\Delta}{=} \left[ \begin{array}{c} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{array} \right] \leftarrow \text{ith row}$$

This vector is considered as having m elements, all of which are 0 except the ith, which is 1.

## Unit Vector u

$$\mathbf{u}_{j} \stackrel{\triangle}{=} \begin{bmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{bmatrix} \leftarrow \text{jth row}$$
as having n elements, all of which as

This vector is considered as having n elements, all of which are 0 except the jth, which is 1.

## The Identity Matrix

Let

$$\mathbf{u}_{1} \stackrel{\Delta}{=} \left[ \begin{array}{c} 1 \\ 0 \\ \vdots \\ \vdots \\ 0 \end{array} \right] \ , \quad \mathbf{u}_{2} \stackrel{\Delta}{=} \left[ \begin{array}{c} 0 \\ 1 \\ \vdots \\ \vdots \\ 0 \end{array} \right] \ , \ldots \, , \quad \mathbf{u}_{n} \stackrel{\Delta}{=} \left[ \begin{array}{c} 0 \\ 0 \\ \vdots \\ \vdots \\ 1 \end{array} \right] \, .$$

Then

$$1 = [\mathbf{u}_1 \quad \mathbf{u}_2 \quad \dots \quad \mathbf{u}_n]$$

is called the identity matrix.

Scalar Product

Let

$$\mathbf{a} \stackrel{\triangle}{=} \left[ \begin{array}{c} \mathbf{a}_1 \\ \mathbf{a}_2 \\ \vdots \\ \vdots \\ \vdots \\ \mathbf{a}_n \end{array} \right], \quad \mathbf{b} \stackrel{\triangle}{=} \left[ \begin{array}{c} \mathbf{b}_1 \\ \mathbf{b}_2 \\ \vdots \\ \vdots \\ \mathbf{b}_n \end{array} \right].$$

Then

$$\mathbf{a}^{\mathsf{T}} \mathbf{b} \stackrel{\Delta}{=} \mathbf{a}_{1} \mathbf{b}_{1} + \mathbf{a}_{2} \mathbf{b}_{2} + \ldots + \mathbf{a}_{n} \mathbf{b}_{n}$$

The result is a scalar.

## Element Selection from Vectors

$$\mathbf{u}_{j}^{\mathrm{T}} \mathbf{a} \equiv \mathbf{a}^{\mathrm{T}} \mathbf{u}_{j} = \mathbf{a}_{j}$$

The result is the scalar element  $a_{j}$ .

$$\mathbf{u}_{i}^{T} \mathbf{a}' \equiv \mathbf{a}^{'T} \mathbf{u}_{i} = \mathbf{a}_{i}^{'}$$

The result is the scalar element  $a_i^{'}$ .

#### Row Selection from Matrices

$$\mathbf{u}_{i}^{T} \mathbf{A} = \mathbf{u}_{i}^{T} \begin{bmatrix} \mathbf{a}_{1}^{T} \\ \mathbf{a}_{2}^{T} \\ \vdots \\ \vdots \\ \mathbf{a}_{m}^{T} \end{bmatrix} = \mathbf{a}_{i}^{T}$$

This result is the row vector corresponding to the ith row of  $\mathbf{A}$ . In transposed form, we have

$$\mathbf{A}^{\mathrm{T}} \mathbf{u}_{i} = \mathbf{a}_{i}$$

## Column Selection from Matrices

$$\mathbf{A}\mathbf{u}_{\mathbf{j}} = [\mathbf{a}_{1}^{'} \quad \mathbf{a}_{2}^{'} \quad \dots \quad \mathbf{a}_{n}^{'}] \quad \mathbf{u}_{\mathbf{j}} = \mathbf{a}_{\mathbf{j}}^{'}$$

This result is the column vector corresponding to the jth column of A. In transposed form, we have

$$\mathbf{u}_{j}^{T} \mathbf{A}^{T} = \mathbf{a}_{j}^{'T}$$

#### **Element Selection from Matrices**

$$\mathbf{u}_{i}^{T} \mathbf{A} \mathbf{u}_{j} = \begin{cases} \mathbf{u}_{i}^{T} (\mathbf{A} \mathbf{u}_{j}) = \mathbf{u}_{i}^{T} \mathbf{a}_{j}^{'} = \mathbf{a}_{ij} \\ (\mathbf{u}_{i}^{T} \mathbf{A}) \mathbf{u}_{j} = \mathbf{a}_{i}^{T} \mathbf{u}_{j} = \mathbf{a}_{ij} \end{cases}$$

This result is the scalar element corresponding to the coefficient of A obtained from the intersection of row i and column j.

#### **Element Representation**

where  $u_j$ , j = 1, ..., n is n-dimensional.

where  $\mathbf{u}_i$ , i = 1, ..., m is m-dimensional.

#### Assembly of an Element into a Column Vector

To place the paramter  $\phi$  into the ith row of a column vector we write

$$\mathbf{u}_{i} \, \Phi = \left[ \begin{array}{c} 0 \\ \vdots \\ \vdots \\ \Phi \\ \vdots \\ \vdots \\ 0 \end{array} \right] \leftarrow \mathrm{ith} \, \mathrm{row}$$

This results in a column vector containing zeros everywhere except in the ith row, which contains  $\boldsymbol{\varphi}.$ 

## Assembly of an Element into a Row Vector

To place the parameter  $\phi$  into the jth column of a row vector we write

This results in a row vector containing zeros everywhere except in the jth column, which contains  $\boldsymbol{\varphi}.$ 

#### Assembly of a Vector into a Row of a Matrix

To place the n-dimensional vector a into the ith row of a matrix we write

$$\mathbf{u}_{i} \, \mathbf{a}^{T} = \left[ \begin{array}{cccc} 0 & 0 & & 0 \\ & \ddots & & & \ddots \\ & \ddots & & & \ddots \\ & \ddots & & & \ddots \\ & 0 & 0 & & 0 \\ & a_{1} & a_{2} & \dots & a_{n} \\ & 0 & 0 & & 0 \\ & \ddots & & & \ddots \\ & \ddots & & & \ddots \\ & \ddots & & & \ddots \\ & 0 & 0 & & 0 \end{array} \right] \leftarrow ith \, row$$

This results in a matrix containing zeros everywhere except in the ith row, which contains  $\mathbf{a}^{T}$ .

#### Assembly of a Vector into a Column of a Matrix

To place the m-dimensional vector a' into the jth column of a matrix we write

This results in a matrix containing zeros everywhere except in the jth column, which contains a'.

#### Assembly of an Element into a Matrix

To place the paramter  $\phi$  into the intersection of row i and column j we write

$$u_i \, \varphi \, u_j^T = \left[ \begin{array}{cccc} & \cdot & & \\ & & \cdot & \\ & & \cdot & \\ & & \cdot & \\ & & \vdots \\ & \vdots \\ & &$$

This results in a matrix containing zeros everywhere except in the i j location, which contains  $\varphi$ .

Two other forms are convenient to represent. The first one is

$$\mathbf{u}_{i} (\phi \, \mathbf{u}_{j}^{T}) = \begin{bmatrix} \mathbf{0}^{T} \\ \mathbf{0}^{T} \\ \vdots \\ \vdots \\ \phi \, \mathbf{u}_{j}^{T} \end{bmatrix} \leftarrow \text{ith row}$$

$$\vdots$$

$$\vdots$$

$$0^{T}$$

The other form is

$$(u_i^{\phantom{T}} \varphi) \ u_j^T = [0 \quad 0 \quad \dots \quad u_i^{\phantom{T}} \varphi \quad \dots \quad 0]$$
 
$$\uparrow \\ ith col$$

## Assembly of a Matrix

To assemble A we may write

$$\mathbf{A} = \sum_{i=1}^{m} \sum_{j=1}^{n} \mathbf{u}_{i} \mathbf{a}_{ij} \mathbf{u}_{j}^{T}$$

## Assembly of the ith Row of a Matrix

To assemble the ith row of A we write

$$\mathbf{a}_{i}^{T} = \sum_{j=1}^{n} \mathbf{a}_{ij} \mathbf{u}_{j}^{T}$$

## Assembly of the jth Column of a Matrix

To assemble the jth column of  $\boldsymbol{A}$  we write

$$\mathbf{a}_{j}^{'} = \sum_{i=1}^{m} \mathbf{u}_{i} \mathbf{a}_{ij}$$

#### Dyadic Product of a and b

Let

$$\mathbf{a} \stackrel{\triangle}{=} \begin{bmatrix} \mathbf{a}_1 \\ \mathbf{a}_2 \\ \vdots \\ \vdots \\ \mathbf{a}_n \end{bmatrix}, \quad \mathbf{b} \stackrel{\triangle}{=} \begin{bmatrix} \mathbf{b}_1 \\ \mathbf{b}_2 \\ \vdots \\ \vdots \\ \mathbf{b}_m \end{bmatrix}$$

Then

$$\mathbf{a} \ \mathbf{b}^{T} \stackrel{\triangle}{=} \left[ \begin{array}{ccccc} a_{1} b_{1} & a_{1} b_{2} & \dots & a_{1} b_{m} \\ a_{2} b_{1} & a_{2} b_{2} & \dots & a_{2} b_{m} \\ & \ddots & & \ddots & & \ddots \\ & \ddots & & \ddots & & \ddots \\ & \vdots & & \ddots & & \ddots \\ & a_{n} b_{1} & a_{n} b_{2} & \dots & a_{n} b_{m} \end{array} \right]$$

This result is the n by m matrix containing all possible products  $a_i$   $b_j$ , i=1,2,...,n; j=1,2,...,m.

## **Definitions of Derivative Operators**

$$\frac{\partial}{\partial \mathbf{a}_{1}} \triangleq \begin{bmatrix} \frac{\partial}{\partial \mathbf{a}_{1}} \\ \frac{\partial}{\partial \mathbf{a}_{2}} \\ \vdots \\ \frac{\partial}{\partial \mathbf{a}_{n}} \end{bmatrix}$$

$$\frac{\partial}{\partial \mathbf{A}} \stackrel{\Delta}{=} \begin{bmatrix} \frac{\partial}{\partial \mathbf{a}_{11}} & \frac{\partial}{\partial \mathbf{a}_{12}} & \cdots & \frac{\partial}{\partial \mathbf{a}_{1n}} \\ \frac{\partial}{\partial \mathbf{a}_{21}} & \frac{\partial}{\partial \mathbf{a}_{22}} & \cdots & \frac{\partial}{\partial \mathbf{a}_{2n}} \\ \vdots & & & \vdots \\ \frac{\partial}{\partial \mathbf{a}_{m1}} & \frac{\partial}{\partial \mathbf{a}_{m2}} & \cdots & \frac{\partial}{\partial \mathbf{a}_{mn}} \end{bmatrix}$$

#### Derivatives of Scalar Products

$$\frac{\partial (\mathbf{a}^{\mathrm{T}}\mathbf{b})}{\partial \mathbf{a}} \ = \ \left( \ \frac{\partial \mathbf{a}^{\mathrm{T}}}{\partial \mathbf{a}} \ \right) \mathbf{b} \ = \ \mathbf{b}$$

Also,

$$\frac{\partial (\mathbf{b}^{\mathrm{T}} \mathbf{a})}{\partial \mathbf{a}} = \frac{\partial (\mathbf{a}^{\mathrm{T}} \mathbf{b})}{\partial \mathbf{a}} = \mathbf{b}$$

#### $\underline{\text{Jacobian Matrix}}[\mathbf{b} \neq \mathbf{a}]$

Let

$$\mathbf{a} \stackrel{\Delta}{=} \left[ \begin{array}{c} \mathbf{a}_1 \\ \mathbf{a}_2 \\ \vdots \\ \vdots \\ \vdots \\ \mathbf{a}_n \end{array} \right], \quad \mathbf{b} \stackrel{\Delta}{=} \left[ \begin{array}{c} \mathbf{b}_1 \\ \mathbf{b}_2 \\ \vdots \\ \vdots \\ \vdots \\ \mathbf{b}_m \end{array} \right]$$

Then

$$\frac{\partial \mathbf{b}^{\mathrm{T}}}{\partial \mathbf{a}} \triangleq \left(\frac{\partial}{\partial \mathbf{a}}\right) \mathbf{b}^{\mathrm{T}} = \begin{bmatrix} \frac{\partial b_{1}}{\partial a_{1}} & \frac{\partial b_{1}}{\partial a_{2}} & \dots & \frac{\partial b_{1}}{\partial a_{n}} \\ \frac{\partial b_{2}}{\partial a_{1}} & \frac{\partial b_{2}}{\partial a_{2}} & \dots & \frac{\partial b_{2}}{\partial a_{n}} \\ \vdots & & & \vdots \\ \frac{\partial b_{m}}{\partial a_{1}} & \frac{\partial b_{m}}{\partial a_{2}} & \dots & \frac{\partial b_{m}}{\partial a_{n}} \end{bmatrix}^{\mathrm{T}}$$

$$= \begin{bmatrix} \left(\frac{\partial b_1}{\partial \mathbf{a}}\right)^T \\ \left(\frac{\partial b_2}{\partial \mathbf{a}}\right)^T \\ \vdots \\ \left(\frac{\partial b_m}{\partial \mathbf{a}}\right)^T \end{bmatrix}$$

$$= \begin{bmatrix} \frac{\partial b_1}{\partial \mathbf{a}} & \frac{\partial b_2}{\partial \mathbf{a}} & \dots & \frac{\partial b_m}{\partial \mathbf{a}} \end{bmatrix}$$

$$= \begin{bmatrix} \frac{\partial \mathbf{b}}{\partial \mathbf{a}_1} & \frac{\partial \mathbf{b}}{\partial \mathbf{a}_2} & \dots & \frac{\partial \mathbf{b}}{\partial \mathbf{a}_n} \end{bmatrix}^T$$

## $\underline{Jacobian\ Matrix}\,[\mathbf{b}\,\equiv\mathbf{a}]$

$$\frac{\partial \mathbf{a}^{T}}{\partial \mathbf{a}} = \begin{bmatrix} \frac{\partial \mathbf{a}_{1}}{\partial \mathbf{a}} & \frac{\partial \mathbf{a}_{2}}{\partial \mathbf{a}} & \dots & \frac{\partial \mathbf{a}_{n}}{\partial \mathbf{a}} \end{bmatrix}$$

$$= [\mathbf{u}_{1} \quad \mathbf{u}_{2} \quad \dots \quad \mathbf{u}_{n}] = \mathbf{1}$$

$$= \begin{bmatrix} \frac{\partial \mathbf{a}}{\partial \mathbf{a}_{1}} & \frac{\partial \mathbf{a}}{\partial \mathbf{a}_{2}} & \dots & \frac{\partial \mathbf{a}}{\partial \mathbf{a}_{n}} \end{bmatrix}^{T}$$

$$= [\mathbf{u}_{1} \quad \mathbf{u}_{2} \quad \dots \quad \mathbf{u}_{n}]^{T} = \mathbf{1}$$

where,

$$\mathbf{a} = \sum_{i=1}^{n} \mathbf{a}_{i} \mathbf{u}_{i}$$

and

$$\frac{\partial}{\partial \mathbf{a}} = \sum_{i=1}^{n} \frac{\partial}{\partial \mathbf{a}_{i}} \mathbf{u}_{i}$$

Hence,

$$\frac{\partial \mathbf{a}}{\partial \mathbf{a}_{i}} \equiv \frac{\partial \mathbf{a}_{i}}{\partial \mathbf{a}} \equiv \mathbf{u}_{i}$$

 $\underline{\text{Jacobian Matrix}}[\mathbf{b} = \mathbf{A} \, \mathbf{a}]$ 

$$\frac{\partial \boldsymbol{b}^T}{\partial \boldsymbol{a}} \ = \ \frac{\partial (\boldsymbol{a}^T \boldsymbol{A}^T)}{\partial \boldsymbol{a}} \ = \ \boldsymbol{A}^T$$

 $\underline{\text{Jacobian Matrix}}[\mathbf{b} = \mathbf{A}^{T} \mathbf{a}]$ 

$$\frac{\partial \mathbf{b}^{\mathrm{T}}}{\partial \mathbf{a}} = \frac{\partial (\mathbf{a}^{\mathrm{T}} \mathbf{A})}{\partial \mathbf{a}} = \mathbf{A}$$

 $\underline{Jacobian\ Matrix}\,[b\ =\ \mathbf{c}^T\ \mathbf{A}\ \mathbf{a}]$ 

$$\frac{\partial \mathbf{b}}{\partial \mathbf{a}} = \mathbf{A}^{\mathrm{T}} \mathbf{c}$$

 $\underline{\text{Jacobian Matrix}}[\mathbf{b} = \mathbf{a}^{\text{T}} \mathbf{A} \mathbf{c}]$ 

$$\frac{\partial \mathbf{b}}{\partial \mathbf{a}} = \mathbf{A} \mathbf{c}$$

 $\underline{Jacobian\ Matrix}\left[b = \mathbf{a}^{T}\,\mathbf{A}\,\mathbf{a}\right]$ 

$$\frac{\partial \mathbf{b}}{\partial \mathbf{a}} = \mathbf{A} \mathbf{a} + \mathbf{A}^{\mathrm{T}} \mathbf{a} = (\mathbf{A} + \mathbf{A}^{\mathrm{T}}) \mathbf{a}$$

## Derivative of an Element of a Matrix w.r.t. A

The result is a matrix with zeros everywhere except at the intersection of row i and column j, which has a 1.

## Derivative of A w.r.t. aij

$$\frac{\partial \mathbf{A}}{\partial \mathbf{a}_{ij}} = \mathbf{u}_i \mathbf{u}_j^T \equiv \frac{\partial \mathbf{a}_{ij}}{\partial \mathbf{A}}$$

## Derivative of $A^{-1}$ where m = n

We have, by definition

$$\mathbf{A}^{-1}\,\mathbf{A} = \mathbf{1}$$

from which

$$\frac{\partial \mathbf{A}^{-1}}{\partial \Phi} = -\mathbf{A}^{-1} \frac{\partial \mathbf{A}}{\partial \Phi} \mathbf{A}^{-1}$$

## Derivative of A-1 w.r.t. aij

$$\frac{\partial \mathbf{A}^{-1}}{\partial \mathbf{a}_{ij}} = -\mathbf{A}^{-1} \mathbf{u}_{i} \mathbf{u}_{j}^{\mathrm{T}} \mathbf{A}^{-1}$$
$$= -\mathbf{p}_{i} \mathbf{q}_{j}^{\mathrm{T}}$$

where  $\mathbf{p}_i$  and  $\mathbf{q}_j$  are solutions to

$$\mathbf{A} \mathbf{p}_{i} = \mathbf{u}_{i}$$

$$\mathbf{A}^{\mathrm{T}}\,\mathbf{q}_{\,j}\,=\,\mathbf{u}_{\,j}^{\phantom{T}}$$

## Derivatives of the Solution of Ax = b

Let  $\mathbf{A}$  be  $n \times n$ ,  $\mathbf{x}$  and  $\mathbf{b}$  be n-dimensional. Then,

$$\frac{\partial \mathbf{x}}{\partial \mathbf{a}_{ij}} = \frac{\partial (\mathbf{A}^{-1} \mathbf{b})}{\partial \mathbf{a}_{ij}}$$
$$= -\mathbf{A}^{-1} \mathbf{u}_i \mathbf{u}_j^T \mathbf{A}^{-1} \mathbf{b} = -\mathbf{p}_i \mathbf{x}_j$$

## Derivative of an Element of the Solution of $\mathbf{A} \mathbf{x} = \mathbf{b}$

Let

$$\frac{\partial \mathbf{x}_{k}}{\partial \mathbf{a}_{ij}} = \mathbf{u}_{k}^{T} \frac{\partial \mathbf{x}}{\partial \mathbf{a}_{ij}} = -\mathbf{u}_{k}^{T} \mathbf{A}^{-1} \mathbf{u}_{i} \mathbf{u}_{j}^{T} \mathbf{A}^{-1} \mathbf{b}$$

$$= -\mathbf{x}_{k}^{T} \mathbf{u}_{i} \mathbf{u}_{j}^{T} \mathbf{x}$$

$$= -\mathbf{x}_{ki}^{T} \mathbf{x}_{j}$$

Hence,

$$\frac{\partial \mathbf{x}_{\mathbf{k}}}{\partial \mathbf{A}} = - \mathbf{\hat{x}}_{\mathbf{k}} \mathbf{x}^{\mathrm{T}}$$

where  $\boldsymbol{\hat{x}}_k$  is the solution of

$$\mathbf{A}^{\mathsf{T}} \, \mathbf{\hat{x}}_{\mathsf{k}}^{\mathsf{r}} = \mathbf{u}_{\mathsf{k}}^{\mathsf{r}}$$

Derivative of a Linear Combination of the Elements of the Solution of  $\mathbf{A} \mathbf{x} = \mathbf{b}$ 

Let 
$$\bar{\mathbf{x}} = \mathbf{u}^{\mathrm{T}} \mathbf{x}$$

Then

$$\frac{\partial \overline{\mathbf{x}}}{\partial \mathbf{a}_{ij}} = \frac{\partial (\mathbf{u}^{\mathrm{T}} \mathbf{x})}{\partial \mathbf{a}_{ij}} = -\mathbf{u}^{\mathrm{T}} \mathbf{p}_{i} \mathbf{q}_{j}^{\mathrm{T}} \mathbf{b}$$
$$= -(\mathbf{u}^{\mathrm{T}} \mathbf{p}_{i}) (\mathbf{b}^{\mathrm{T}} \mathbf{q}_{j})$$

The result comes from the appropriate linear combinations of  $\boldsymbol{p}_i$  and  $\boldsymbol{q}_j$ 

Alternatively,

$$\frac{\partial \overline{\mathbf{x}}}{\partial \mathbf{a}_{ij}} = -\mathbf{q}^{\mathrm{T}} \mathbf{u}_{i} \mathbf{u}_{j}^{\mathrm{T}} \mathbf{x}$$
$$= -\mathbf{q}_{i} \mathbf{x}_{j}$$

where q is the solution of

$$\mathbf{A}^{\mathrm{T}}\mathbf{q}=\mathbf{u}$$

Hence

$$\frac{\partial \mathbf{\bar{x}}}{\partial \mathbf{A}} = -\mathbf{q} \; \mathbf{x}^{\mathrm{T}}$$

Also,

$$\frac{\partial \overline{\mathbf{x}}}{\partial \mathbf{a}_{ij}} = \mathbf{u}_i^T \frac{\partial \overline{\mathbf{x}}}{\partial \mathbf{A}} \mathbf{u}_j$$

Hence

$$\frac{\partial \overline{x}}{\partial \varphi} \ = \ \sum_{i \, = \, 1}^n \ \sum_{j \, = \, 1}^n \ \frac{\partial \overline{x}}{\partial a_{\,ij}} \ \frac{\partial a_{\,ij}}{\partial \varphi} \ = \ \sum_{i \, = \, 1}^n \ \sum_{j \, = \, 1}^n \ u_i^T \ \frac{\partial \overline{x}}{\partial A} \ u_j \ \frac{\partial a_{\,ij}}{\partial \varphi}$$

Special Case 1

Let

$$\frac{\partial \mathbf{A}}{\partial \Phi} \equiv \mathbf{u} \, \mathbf{u}_{i}^{\mathrm{T}} - \mathbf{u} \, \mathbf{u}_{j}^{\mathrm{T}}$$

Then

$$\frac{\partial \overline{\mathbf{x}}}{\partial \mathbf{\phi}} = -\mathbf{u}^{\mathrm{T}} \frac{\partial \mathbf{x}}{\partial \mathbf{\phi}} = -\mathbf{u}^{\mathrm{T}} \mathbf{A}^{-1} \frac{\partial \mathbf{A}}{\partial \mathbf{\phi}} \mathbf{A}^{-1} \mathbf{b}$$

$$= -\mathbf{u}^{\mathrm{T}} \mathbf{A}^{-1} \mathbf{u} (\mathbf{u}_{i} - \mathbf{u}_{j})^{\mathrm{T}} \mathbf{A}^{-1} \mathbf{b}$$

$$= -\mathbf{u}^{\mathrm{T}} \mathbf{p} (\mathbf{x}_{i} - \mathbf{x}_{j})$$

Let

$$\mathbf{u} = \mathbf{u}_{i} - \mathbf{u}_{j}$$

Then

$$\frac{\partial \overline{x}}{\partial \Phi} = -(p_i - p_j)(x_i - x_j)$$

and

$$\frac{\partial \mathbf{A}}{\partial \Phi} = (\mathbf{u}_i - \mathbf{u}_j)(\mathbf{u}_i - \mathbf{u}_j)^T$$

## Special Case 2

Let

$$\frac{\partial \mathbf{A}}{\partial \Phi} \equiv (\mathbf{u}_{k} - \mathbf{u}_{\ell}) (\mathbf{u}_{k} - \mathbf{u}_{\ell})^{\mathrm{T}}$$

Then

$$\frac{\partial \overline{\mathbf{x}}}{\partial \Phi} = -\mathbf{u}^{\mathrm{T}} \mathbf{A}^{-1} (\mathbf{u}_{k} - \mathbf{u}_{\ell}) (\mathbf{u}_{k} - \mathbf{u}_{\ell})^{\mathrm{T}} \mathbf{A}^{-1} \mathbf{b}$$
$$= - (\mathbf{q}_{k} - \mathbf{q}_{\ell}) (\mathbf{x}_{k} - \mathbf{x}_{\ell})$$

where q is the solution to

$$\mathbf{A}^{\mathrm{T}}\mathbf{q}=\mathbf{u}$$

and  $\mathbf{u}$  is the vector leading to  $\mathbf{\bar{x}} = \mathbf{u}^T \mathbf{x}$ .

## Placing Elements Arbitrarily

Let

$$\mathbf{u}_0 \stackrel{\Delta}{=} \left[ \begin{array}{c} 0 \\ 0 \\ \vdots \\ \vdots \\ 0 \end{array} \right]$$

$$\mathbf{u}_{1} \overset{\Delta}{=} \begin{bmatrix} 1 \\ 0 \\ \vdots \\ \vdots \\ 0 \end{bmatrix}$$

$$\mathbf{u}_{2} \stackrel{\Delta}{=} \left[ \begin{array}{c} \mathbf{0} \\ \mathbf{1} \\ \cdot \\ \cdot \\ \cdot \\ \mathbf{0} \end{array} \right]$$

$$\mathbf{u}_{\mathbf{n}} \stackrel{\triangle}{=} \left[ \begin{array}{c} 0 \\ 0 \\ \vdots \\ \vdots \\ 1 \end{array} \right]$$

and denote

$$\mathbf{u}_{i,j} \stackrel{\Delta}{=} \mathbf{u}_i - \mathbf{u}_j$$

$$\mathbf{u}_{\mathrm{rs},k\ell} \stackrel{\Delta}{=} \mathbf{u}_{\mathrm{r}} + \mathbf{u}_{\mathrm{s}} - \mathbf{u}_{\mathrm{k}} - \mathbf{u}_{\ell}$$

hence

$$\mathbf{u}_{i_1 i_2 \cdots i_p, j_1 j_2 \cdots j_q} \stackrel{\Delta}{=} \sum_{k=1}^p \mathbf{u}_{i_k} - \sum_{\ell=1}^q \mathbf{u}_{j_\ell}$$

For example,

$$\mathbf{u}_{345,16} = \begin{bmatrix} -1 \\ 0 \\ 1 \\ 1 \\ 1 \\ -1 \end{bmatrix}$$

Then if

$$\mathbf{u} \equiv \mathbf{u}_{345,16}$$

we have

$$\mathbf{u}^{\mathrm{T}}\mathbf{u} = \operatorname{card}\{3, 4, 5, 1, 6\} = 5$$

and

$$\mathbf{u} \, \mathbf{u}^{\mathrm{T}} = \begin{bmatrix} 1 & 0 & -1 & -1 & -1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ -1 & 0 & 1 & 1 & 1 & -1 \\ -1 & 0 & 1 & 1 & 1 & -1 \\ -1 & 0 & 1 & 1 & 1 & -1 \\ 1 & 0 & -1 & -1 & -1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \end{bmatrix}$$

$$= (\mathbf{u}_3 + \mathbf{u}_4 + \mathbf{u}_5 - \mathbf{u}_1 - \mathbf{u}_6)(\mathbf{u}_3 + \mathbf{u}_4 + \mathbf{u}_5 - \mathbf{u}_1 - \mathbf{u}_6)^{\mathrm{T}}$$

