

**BSTALN - A COMPUTER IMPLEMENTATION
OF AN ALGORITHM FOR THE BEST
MECHANICAL ALIGNMENT PROBLEM**

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BSTALN - A COMPUTER IMPLEMENTATION OF AN ALGORITHM
FOR THE BEST MECHANICAL ALIGNMENT PROBLEM

J.W. Bandler, M.A. El-Kady, W. Kellermann and W.M. Zuberek

Abstract

BSTALN is a Fortran implementation of a recently developed minimax approach to the best mechanical alignment problem in two dimensions. The program employs the MMLC package for linearly constrained minimax optimization, which must be made available. The BSTALN program is composed of a main segment and nine subroutines. The listing contains 941 lines, 335 of which are comments. The program and documentation have been developed for the CDC 170/730 system with the NOS 1.4 level 552 operating system and the Fortran Extended (FTN) version 4.8 compiler. This document contains a Fortran listing of the program.

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I. INTRODUCTION

A recently developed minimax approach to the best mechanical alignment problem in two dimensions [1] has been implemented as a Fortran IV program [2] for the CDC 170/730 system. The BSTALN program for solving the problem employs the MMLC package for linearly constrained minimax optimization [3], which must be made available when BSTALN is used.

The data files, created according to the format described in [2], must also be supplied.

The BSTALN program is composed of a main segment and nine subroutines. The listing contains 941 lines, 335 of which are comments.

The program and documentation have been developed for the CDC 170/730 system with NOS 1.4 level 552 operating system and the Fortran Extended (FTN) version 4.8 compiler.

This document contains a Fortran listing of the program.

II. REFERENCES

- [1] J.W. Bandler, M.A. El-Kady, W. Kellermann and W.M. Zuberek, "A minimax approach to the best mechanical alignment problem", Department of Electrical and Computer Engineering, McMaster University, Hamilton, Canada, Report SOS-82-10-R, 1982. Also to appear in ASME J. of Mechanisms, Transmissions, and Automation in Design.
- [2] J.W. Bandler, M.A. El-Kady, W. Kellermann and W.M. Zuberek, "BSTALN - a computer implementation of an algorithm for the best mechanical alignment problem", Department of Electrical and Computer Engineering, McMaster University, Hamilton, Canada, Report SOS-83-13-U, 1983.
- [3] J.W. Bandler and W.M. Zuberek, "MMLC - a Fortran package for linearly constrained minimax optimization", Department of Electrical and Computer Engineering, McMaster University, Hamilton, Canada, Report SOS-82-5-U/L, 1982.

III. LISTING OF THE BSTALN PROGRAM

<u>Subroutine</u>	<u>Number of lines</u> (source text)	<u>Number of words</u> (compiled code)	<u>Listing from page</u>
BSTALN	183	1171	4
PRSRCH	49	144	6
SEARCH	169	625	7
INSRCH	74	301	10
SOLVER	106	605	11
FDF	146	557	12
TOLCIR	40	61	15
TOLXY	55	112	15
TOLXR	60	125	16
TOLYR	59	125	17

```

PROGRAM BSTALN(SAMPLE,OUTPUT,TAPE1=SAMPLE,TAPE6=OUTPUT)
THIS PROGRAM SOLVES THE BEST ALIGNMENT PROBLEM USING
MINIMAX OPTIMIZATION (PACKAGE MMLC).
XA - VECTOR OF ACTUAL X DIMENSIONS(ABSOLUTE)
YA - VECTOR OF ACTUAL Y DIMENSIONS(ABSOLUTE)
KTC - TOLERANCE CODE VECTOR
KOC - ORIGIN CODE VECTOR
T1 - TOLERANCE REGION PARAMETER VECTOR(ABSOLUTE)
T2 - TOLERANCE REGION PARAMETER VECTOR(ABSOLUTE)
T3 - TOLERANCE REGION PARAMETER VECTOR(ABSOLUTE)
T4 - TOLERANCE REGION PARAMETER VECTOR(ABSOLUTE)
T10 - TOLERANCE REGION PARAMETER VECTOR(RELATIVE)
T20 - TOLERANCE REGION PARAMETER VECTOR(RELATIVE)
T30 - TOLERANCE REGION PARAMETER VECTOR(RELATIVE)
T40 - TOLERANCE REGION PARAMETER VECTOR(RELATIVE)
XP - VECTOR OF ACTUAL X DIMENSIONS(RELATIVE)
YP - VECTOR OF ACTUAL Y DIMENSIONS(RELATIVE)
P - PARAMETER SELECTING CANDIDATES FOR DELETING
MD - MODE VECTOR INDICATING THE TYPE OF A POINT
    MD(I)=0 REGULAR POINT
    MD(I)>0 REFERENCE POINT
    MD(I)<0 REFERENCED POINT
NRF - VECTOR OF CURRENT RESIDUAL FUNCTION ORDERING
NRFF- VECTOR OF RESIDUAL FUNCTION ORDERING AT THE SOLUTION
N - NUMBER OF INITIAL VARIABLES
M - TOTAL NUMBER OF RESIDUAL FUNCTIONS
X - VECTOR OF INITIAL VALUES OF VARIABLES
YX - VECTOR OF THE BEST SOLUTION
W - WORKSPACE FOR *SEARCH* AND MINIMAX
IW - LENTGH OF W
IM - LENTGH OF WORKSPACE FOR MINIMAX
NUM - NUMBER OF ELIMINATED RESIDUAL FUNCTIONS
MI - CURRENT NUMBER OF RESIDUAL FUNCTIONS
IFLG- RETURN FLAG FROM *PRSRCH*
L - COUNTER OF RESIDUAL FUNCTIONS WITH POSITIVE VALUE

DIMENSION X(13),W(2000),T(4),NRFF(20),XX(13)
COMMON /BL1/XA(20),YA(20)
COMMON /BL2/KTC(20),T1(20),T2(20),T3(20),T4(20)
COMMON /BL3/T10(20),T20(20),T30(20),T40(20)
COMMON /BL4/KOC(20),MD(20)
COMMON /BL5/NRF(20)
COMMON /BL6/XP(20),YP(20)
COMMON /BL7/PARAM
DATA T(1)/10H HOLES C /
CALL SECOND(TIME1)
CALL DATE(DAT)
CALL TIME(TIM)
REWIND 1

READ AND PRINT INPUT DATA FOR THE PROBLEM

WRITE(6,100)DAT,TIM
100 FORMAT(/" INPUT DATA FOR THE BEST ALIGNMENT PROBLEM DATE :",
1A9," TIME :",A10/)
READ(1,200)M,PARAM,T(2),T(3),T(4)
200 FORMAT(I2,F6.4,2X,3A10)
WRITE(6,300)M,T(1),T(2),T(3),T(4)
300 FORMAT(/" TOTAL NUMBER OF HOLES OF THE SAMPLE:",I3,5X,4A10/)
WRITE(6,600)
600 FORMAT(/2X,"I",6X,"KTC(I)",1X,"KOC(I)",8X,"XA(I)",9X,
1"YA(I)",9X,"T1(I)",9X,"T2(I)",9X,"T3(I)",9X,"T4(I)")
DO 10 I=1,M

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	READ(1,400)KTC(I),KOC(I),XA(I),YA(I),T1(I),T2(I),T3(I),T4(I)	000066
400	FORMAT(2I3,6F8.0)	000067
	WRITE(6,500)I,KTC(I),KOC(I),XA(I),YA(I),T1(I),T2(I),T3(I),T4(I)	000068
500	FORMAT(/1X,12,6X,15,2X,15,1X,6(F13.6,1X))	000069
	10 CONTINUE	000070
C		000071
C	FORM VECTORS XP AND YP	000072
C		000073
	DO 20 I=1,M	000074
	XP(I)=XA(I)	000075
	YP(I)=YA(I)	000076
	20 CONTINUE	000077
C		000078
C	FORM VECTORS T10,T20,T30,T40	000079
C		000080
	DO 25 I=1,M	000081
	T10(I)=T1(I)	000082
	T20(I)=T2(I)	000083
	T30(I)=T3(I)	000084
	T40(I)=T4(I)	000085
	25 CONTINUE	000086
	IW=2000	000087
	IM=1402	000088
C		000089
C	SET INITIAL VALUES OF VARIABLES	000090
C		000091
	X(1)=0.0	000092
	X(2)=0.0	000093
	X(3)=0.0	000094
C		000095
C	CALCULATE ABSOLUTE DIMENSIONS XA,YA AND	000096
C	TOLERANCE REGION PARAMETERS T1,T2,T3,T4	000097
C		000098
	DO 30 I=1,M	000099
	J=KOC(I)	000100
	IF(J.EQ.0)GO TO 30	000101
	XA(I)=XA(I)+XA(J)	000102
	YA(I)=YA(I)+YA(J)	000103
	IF(KTC(I).EQ.0)GO TO 40	000104
	IF(KTC(I).EQ.12)GO TO 50	000105
	IF(KTC(I).EQ.13)GO TO 60	000106
	IF(KTC(I).EQ.23)GO TO 70	000107
40	T1(I)=T1(I)+XA(J)	000108
	T2(I)=T2(I)+YA(J)	000109
	GO TO 30	000110
50	T1(I)=T1(I)+XA(J)	000111
	T2(I)=T2(I)+XA(J)	000112
	T3(I)=T3(I)+YA(J)	000113
	T4(I)=T4(I)+YA(J)	000114
	GO TO 30	000115
60	T1(I)=T1(I)+XA(J)	000116
	T2(I)=T2(I)+XA(J)	000117
	GO TO 30	000118
70	T1(I)=T1(I)+YA(J)	000119
	T2(I)=T2(I)+YA(J)	000120
	30 CONTINUE	000121
C		000122
C	INITIALIZE VECTOR OF CURRENT RESIDUAL FUNCTION ORDERING	000123
C		000124
	DO 33 I=1,M	000125
33	NRF(I)=I	000126
C		000127
C	INITIALIZE MODE VECTOR	000128
C		000129
	DO 37 J=1,M	000130

```
37 MD(J)=0
C
C      CALCULATE RESIDUAL FUNCTIONS AT THE STARTING POINT
C
      CALL FDF(3,M,X,W(M+1),W(1))
      WRITE(6,700)(I,W(I),I=1,MD)
700  FORMAT(////" ERROR FUNCTIONS AT THE STARTING POINT"//(25X,
      1I3,1X,1PE15.7))
C
C      CHECK THE SIGN OF RESIDUAL FUNCTIONS AT THE STARTING POINT
C
      L=0
      DO 19 I=1,M
      IF(W(I).GT.0.0)L=L+1
19  CONTINUE
C
C      BEGIN THE ALIGNMENT
C
      CALL PRSRCH(13,3,M,X,XX,NUM,FM,NRFF,L,W,IW,IM,IFLG)
      IF(IFLG.LT.0)GO TO 90
C
C      PRINT FINAL RESULTS OF THE ALIGNMENT
C
      WRITE(6,800)IFLG,XX(1),XX(2),XX(3),FM
800  FORMAT(////" SOLUTION (TYPE: ",I2," )"/,3(/29X,1PE15.7)//
      1" MAX ERROR AT THE SOLUTION: ",2X,1PE15.7//)
      MM=M-NUM
      WRITE(6,810)(NRFF(I),W(I),I=1,MD)
310  FORMAT(25X,I3,1X,1PE15.7)
      WRITE(6,820)NUM
820  FORMAT(/" NUMBER OF DELETIONS: ",20X,I3/)
      MM=MM+1
      IF(NUM.LE.0)GO TO 999
      L=2
      DO 75 I=MM,M
      IF(W(I).GT.0.0)GO TO 76
      L=L+2
      WRITE(6,830)NRFF(I),W(I),XX(L),XX(L+1)
830  FORMAT(25X,I3,1X,1PE15.7,3X,2(1PE15.7))
      GO TO 75
      76 WRITE(6,830)NRFF(I),W(I)
      75 CONTINUE
      GO TO 999
      STOP
      90 WRITE(6,990)IFLG
990  FORMAT(////" ERROR RETURN FROM SEARCH: ",I3/)
999  CALL SECOND(TIME2)
      EXTIME=TIME2-TIME1
      WRITE(6,805)EXTIME
805  FORMAT(/" TOTAL EXECUTION TIME : ",F7.3," SECONDS")
      STOP
      END
C
C
      SUBROUTINE PRSRCH(NX,N,M,X,XX,NUM,FM,NRFF,LIM,W,LW,LM,IFLG)
      DIMENSION X(N),XX(NX),NRFF(MD),W(LW)
C
C      THIS SUBROUTINE ORGANIZES WORKSPACE MEMORY FOR *SEARCH* AND SETS
C      THE RETURN FLAG *IFLG* :
C      -2  ERROR RETURN FROM *SOLVER* OR MINIMAX,
C      -1  INSUFFICIENT WORKSPACE,
C      0   SOLUTION OBTAINED,
C      1   LARGER WORKSPACE REQUIRED,
C      2   LIMIT OF LEVELS REACHED.
C
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C      NOTE: FOR L-LEVEL SEARCH OF K-DECISION-TREE THE LENGTH "LLI"      000261
C      OF WORKSPACE "LLIND" SHOULD BE APPROXIMATELY K**(L+1).          000262
C                                                                           000263
C      FOR SUBPROBLEM MINIMAX OPTIMIZATION SUBROUTINE *SOLVER* IS      000264
C      CALLED:                                                            000265
C                                                                           000266
C      CALL SOLVER (NN,MM,M,XR,F,NRF,LLIND,LL,NR,W,LW,IERR)           000267
C                                                                           000268
C      NN - NUMBER OF VARIABLES,                                         000269
C      MM - CURRENT NUMBER OF RESIDUAL FUNCTIONS,                       000270
C      M - TOTAL NUMBER OF RESIDUAL FUNCTIONS,                          000271
C      XR - VECTOR OF INITIAL VALUES AND MINIMAX SOLUTION,            000272
C      F - VALUE OF MINIMAX FUNCTION AT SOLUTION,                       000273
C      NRF - VECTOR OF CURRENT RESIDUAL FUNCTION ORDERING,             000274
C      LLIND - SUBSCRIPTS OF DECISION-TREE STRUCTURE,                  000275
C      LL - CURRENT LENGTH OF LLIND,                                     000276
C      NR - INDEX OF LAST VALUE STORED IN LLIND,                        000277
C      W - WORKSPACE FOR MINIMAX,                                       000278
C      LW - LENGTH OF W,                                                000279
C      IERR - RETURN FLAG FROM *SOLVER*.                                000280
C                                                                           000281
C      NOTE: IT IS ASSUMED THAT THE SUBROUTINE *SOLVER* STORES IN LLIND 000282
C      NUMBERS (INDEXES) OF THOSE RESIDUAL FUNCTIONS WHICH ARE          000283
C      CANDIDATES FOR ELIMINATION IN FURTHER STEPS. NUMBER OF          000284
C      THOSE CANDIDATES FOR CURRENT SUBPROBLEM IS ASSUMED TO BE        000285
C      RETURNED AS "IERR" (IERR=0 INDICATES FINAL SOLUTION, I.E.      000286
C      NO CANDIDATES FOR ELIMINATION). ENTERING CANDIDATE NUMBERS     000287
C      INTO *LLIND* SHOULD FOLLOW THE SEQUENCE:                          000288
C                                                                           000289
C      IF (NR.GE.LL) GO TO 123                                           000290
C      NR=NR+1                                                            000291
C      LLIND(NR)=CURRENT.NUMBER.OF.CANDIDATE.RESIDUAL.FUNCTION        000292
C      123 CONTINUE                                                       000293
C                                                                           000294
C      NEGATIVE VALUES OF *IERR* INDICATE ERRORS DETECTED IN         000295
C      MINIMAX OR *SOLVER*.                                             000296
C                                                                           000297
C      DATE : 82.06.21 (W.M.ZUBEREKO)                                    000298
C                                                                           000299
C      FINISH=.FALSE.                                                    000300
C      CLOSED=.FALSE.                                                    000301
C      IER=-1                                                              000302
C      LIMIT=MIN0(LIM,M-1)                                               000303
C      DO 9 I=1,N                                                         000304
C 9  XR(I)=XC(I)                                                           000305
C      DO 10 I=1,M                                                         000306
C      NRFF(I)=1                                                           000307
C 10 NRF(I)=I                                                             000308
C      NUM=0                                                               000309
C      NR=0                                                                000310
C      NN=N                                                                000311
C      CALL SOLVER(NN,M,M,XR,FMIN,NRF,LLIND,LLI,NR,W,LW,IE)            000312
C      IF(IE.LT.0) RETURN                                                 000313
C      DO 11 I=1,M                                                         000314
C 11 FF(I)=W(I)                                                           000315
C      NMK=NN                                                              000316
C      DO 12 I=1,NN                                                        000317
C 12 XX(I)=XR(I)                                                           000318
C      IF(IE.EQ.0) GOTO 80                                                000319
C      LLIND(LLI)=NR                                                       000320
C      LLC=LLI-1                                                           000321
C      MAXLEV=0                                                            000322
C      M1=M+1                                                              000323
C 15 IF(LCH.GT.0) WRITE(LCH,111) MAXLEV,FMIN                             000324
C 111 FORMAT(///" STAGE: ",I3,14X,"FMAX: ",1PE15.7/)                   000325

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IF(LCH.GT.0) WRITE(LCH,112) (I,NRFF(I),FF(I),I=1,M)
112 FORMAT(18X,214,3X,1PE15.7)
MAXLEV=MAXLEV+1
LEV=1
LL=1
20 L=1
IF(LEV.GT.1) L=LL+1
LL=1
LR=LLI+1-L
IF(L.GT.1) LL=LLIND(LR+1)+1
LACT(LEV)=LL
30 J=LLIND(LL)
IF(J.GT.0) GOTO 35
IF(NR.GE.LLC) GOTO 33
NR=NR+1
LLIND(NR)=0
33 LLIND(LLC)=NR
LLC=LLC-1
IF(LLC.LE.NR) CLOSED=.TRUE.
GOTO 55
35 JJ=M1-LEV
I=NRFF(J)
NRFF(J)=NRFF(JJ)
NRFF(JJ)=I
IF(LEV.EQ.MAXLEV) GOTO 40
LEV=LEV+1
GOTO 20
40 MM=M-MAXLEV
NN=N
NRR=NR+1
DO 41 I=1,N
41 XR(I)=X(I)
CALL SOLVER(NN,MM,M,XR,F,NRF,LLIND,LLC,NR,W,LW,IE)
IF(IE.LT.0) RETURN
IF(FMIN.LE.F) GOTO 44
FMIN=F
DO 42 I=1,NN
42 XX(I)=XR(I)
NMX=NN
DO 43 I=1,M
FF(I)=W(I)
43 NRFF(I)=NRF(I)
NUM=LEV
44 IF(IE.NE.0) GOTO 45
FINISH=.TRUE.
GOTO 50
45 IF(CLOSED) GOTO 50
IF(LLC.LE.NR) CLOSED=.TRUE.
LLIND(LLC)=NR
LLC=LLC-1
IF(CLOSED.OR.FINISH) GOTO 50
CALL INSRCH(NRR,NR,MAXLEV,M,NRF,LLIND,LLI,W,W(M1))
50 I=NRFF(J)
NRFF(J)=NRFF(JJ)
NRFF(JJ)=I
55 IF(LACT(LEV).GE.LLIND(LR)) GOTO 60
LL=LACT(LEV)+1
LACT(LEV)=LL
GOTO 30
60 LEV=LEV-1
IF(LEV.EQ.0) GOTO 70
L=1
IF(LEV.GT.1) L=LACT(LEV-1)+1
LR=LLI+1-L
LL=LACT(LEV)
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J=LLIND(LL)
JJ=M1-LEV
GOTO 50
70 IF(FINISH.OR.CLOSED) GOTO 90
   IF(MAXLEV.GE.LIMIT) GOTO 90
   GOTO 15
80 FINISH=.TRUE.
90 IER=0
   RETURN
   END
C
C
SUBROUTINE INSRCH(NRR, NR, MAXLEV, M, NRF, LLIND, LLI, LACT, NFF)
DIMENSION NRF(M), LLIND(LLI), LACT(M), NFF(M)
C
C THIS SUBROUTINE ELIMINATES IDENTICAL ENTRIES IN DECISION-TREE
C STRUCTURE DESCRIBED IN *LLIND*.
C
C NRR - LOCATION OF THE FIRST OF NEW ENTRIES,
C NR - LOCATION OF THE LAST OF NEW ENTRIES,
C MAXLEV - CURRENT NUMBER OF LEVELS,
C M - TOTAL NUMBER OF RESIDUAL FUNCTIONS,
C NRF - ORDERING OF RESIDUAL FUNCTIONS,
C LLIND - INDEX AND SUBSCRIPTS OF DECISION-TREE STRUCTURE,
C LLI - LENGTH OF *LLIND*,
C LACT - VECTOR OF CURRENT COUNTS (WORKSPACE),
C NFF - CURRENT ORDERING OF RESIDUAL FUNCTIONS.
C
DATE : 82.06.21 (W.M.ZUBEREK)
C
DIMENSION NPW(20)
DATA NPW/1,2,4,8,16,32,64,128,256,512,1024,2048,4096,8192,16384,
1 32768,65536,131072,262144,524288/
M1=M+1
NRN=0
MM=M1-MAXLEV
DO 10 I=MM, M
K=NRF(I)
10 NRN=OR(NRN, NPW(K))
DO 60 I=NRR, NR
DO 15 J=1, M
15 NFF(J)=J
K=LLIND(I)
K=NRF(K)
NRA=OR(NRN, NPW(K))
LEV=0
LL=1
20 LEV=LEV+1
L=1
IF(LEV.GT.1) L=LL+1
LL=1
LR=LLI+1-L
IF(L.GT.1) LL=LLIND(LR+1)+1
LACT(LEV)=LL
30 IF(LL.GE.NRR) GOTO 60
J=LLIND(LL)
IF(J.EQ.0) GOTO 45
JJ=M1-LEV
K=NFF(J)
NFF(J)=NFF(JJ)
NFF(JJ)=K
IF(AND(NRA, NPW(K)).EQ.0) GOTO 40
IF(LEV.LE.MAXLEV) GOTO 20
LLIND(I)=0
GOTO 60

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40 JJ=M1-LEV                                000456
   K=NFF(J)                                  000457
   NFF(J)=NFF(JJ)                            000458
   NFF(JJ)=K                                  000459
45 IF(LACT(LEV).GE.LLIND(LR)) GOTO 50        000460
   LL=LACT(LEV)+1                             000461
   LACT(LEV)=LL                               000462
   GOTO 30                                     000463
50 LEV=LEV-1                                  000464
   IF(LEV.EQ.0) GOTO 60                       000465
   L=1                                         000466
   IF(LEV.GT.1) L=LACT(LEV-1)+1              000467
   LR=LLI+1-L                                 000468
   LL=LACT(LEV)                               000469
   J=LLIND(LL)                               000470
   GOTO 40                                     000471
60 CONTINUE                                  000472
   RETURN                                     000473
   END                                         000474

C
C
SUBROUTINE SOLVER(NN, M, MF, X, F, NFR, LIND, LL, NR, W, IW, IERR) 000475
DIMENSION X(1), LIND(LL), W(IW), NFR(1) 000476

C
C
THIS SUBROUTINE PREPARES PARAMETERS AND CALLS MINIMAX OPTIMIZATION 000477
ROUTINE MMLA1Q, ALSO PRINTS RESULTS OF MINIMAX OPTIMIZATION. 000478

C
C
NN - NUMBER OF VARIABLES 000479
M - CURRENT NUMBER OF RESIDUAL FUNCTIONS 000480
MF - TOTAL NUMBER OF RESIDUAL FUNCTIONS 000481
X - VECTOR OF INITIAL VALUES AND MINIMAX SOLUTION 000482
F - VALUE OF MINIMAX FUNCTION AT THE SOLUTION 000483
NFR - VECTOR OF CURRENT RESIDUAL FUNCTION ORDERING 000484
LIND- SUBSCRIPTS OF DECISION-TREE STRUCTURE 000485
LL - CURRENT LENGTH OF LIND 000486
NR - INDEX OF LAST VALUE STORED IN LIND 000487
W - WORKSPACE FOR MINIMAX 000488
IW - LENGTH OF W 000489
IERR- RETURN FLAG FROM *SOLVER* 000490

C
C
COMMON /BL1/XA(20), YA(20) 000491
COMMON /BL4/KOC(20), MD(20) 000492
COMMON /BL7/PARAM 000493
COMMON /BL5/NRF(20) 000494
EXTERNAL FDF 000495
DATA SP/1H /, ST/1H*/ 000496
MM=M 000497
DO 5 I=1, MF 000498
5 NRF(I)=NFR(I) 000499
DO 10 I=1, MF 000500
10 MD(I)=0 000501
   IF(M.EQ.MF) GO TO 50 000502
   M1=M+1 000503
   DO 30 I=M1, MF 000504
   DO 20 J=1, M 000505
   K=NRF(J) 000506
   IF(KOC(K).EQ.NRF(I)) GO TO 25 000507
20 CONTINUE 000508
   GO TO 30 000509
25 MM=MM+1 000510
   NRR=NRF(I) 000511
   NRF(I)=NRF(MM) 000512
   NRF(MM)=NRR 000513
   X(NN+1)=XA(NRR) 000514
   X(NN+2)=YA(NRR) 000515

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MD(NRR) = NN+1
DO 26 J=1, M
K=NRF(J)
IF(KOC(K).EQ.NRR) MD(K)=-NN-1
26 CONTINUE
NN=NN+2
30 CONTINUE
50 L=0
LEQ=0
IC=0
DX=0.001
EPS=1.E-6
MAXF=25
KEQS=3
CALL MMLA1Q(FDF, NN, MM, L, LEQ, W, W, IC, X, DX, EPS, MAXF, KEQS, W, IW, IFL)
IF(IFL.LT.0) GO TO 99
F=W(1)
DO 52 I=2, MM
52 F=AMAX1(F, W(I))
WRITE(6,100) IFL, F, MAXF, KEQS
100 FORMAT(/" RESULT OF MINIMAX OPTIMIZATION (RETURN: ", I2,
1)"", 1PE15.7, 5X, "N.IT: ", I3, 3X, "N.SH: ", I3/)
IF(F.GT.0.0) GOTO 60
NM=MAX0(NN, MM)
DO 55 I=1, NM
Z=SP
J=NRF(I)
IF(MD(J).GT.0) Z=ST
IF(I.LE.NN.AND.I.LE.MM) WRITE(6,101) I, X(I), NRF(I), W(I), Z
IF(I.GT.NN) WRITE(6,102) NRF(I), W(I), Z
IF(I.GT.MM) WRITE(6,101) I, X(I)
55 CONTINUE
101 FORMAT(5X, I3, 1X, 1PE15.7, I4, 1X, 1PE15.7, 1X, A1)
102 FORMAT(25X, I3, 1X, 1PE15.7, 1X, A1)
60 IERR=0
DO 70 I=1, M
IF(W(I).LE.PARAM*F) GO TO 70
IERR=IERR+1
IF(NR.GE.LL) GO TO 70
NR=NR+1
LIND(NR)=I
70 CONTINUE
ME=MF-M
IF(ME.EQ.0) GOTO 90
MB=MM
DO 81 I=1, ME
J=MF+1-I
K=NRF(J)
Z=1.E99
IF(MD(K).LE.0) GOTO 80
Z=W(MB)
MB=MB-1
80 W(J)=Z
81 CONTINUE
90 RETURN
99 WRITE(6,900) IFL
900 FORMAT(///" ERROR RETURN FROM MINIMAX: ", I3)
IERR=-1
RETURN
END

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C
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C

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SUBROUTINE FDF(N, M, K, DF, F)
DIMENSION X(N), F(M), DF(M, N), DX3(20), DY3(20), XA1(20), YA1(20)

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C THIS SUBROUTINE PERFORMS TRANSFORMATION OF COORDINATES, 000586
C EVALUATES RESIDUAL FUNCTIONS AND CALCULATES FINAL 000587
C DERIVATIVES. 000588
C 000589
C N - NUMBER OF VARIABLES 000590
C M - NUMBER OF RESIDUAL FUNCTIONS 000591
C X - VECTOR OF VALUES OF VARIABLES 000592
C DF - MATRIX OF RESIDUAL FUNCTION DERIVATIVES W.R.T. 000593
C OPTIMIZATION VARIABLES AT POINT X 000594
C F - VECTOR OF VALUES OF RESIDUAL FUNCTIONS AT POINT X 000595
C 000596
COMMON /BL1/XA(20), YA(20) 000597
COMMON /BL2/KTC(20), T1(20), T2(20), T3(20), T4(20) 000598
COMMON /BL3/T10(20), T20(20), T30(20), T40(20) 000599
COMMON /BL4/KOC(20), MD(20) 000600
COMMON /BL5/NRF(20) 000601
COMMON /BL6/XP(20), YP(20) 000602
X1=X(1) 000603
X2=X(2) 000604
X3=X(3) 000605
C 000606
C TRANSFORMATION OF COORDINATES 000607
C 000608
SN=SIN(X3) 000609
CS=COS(X3) 000610
DO 10 I=1, M 000611
J=NRF(I) 000612
XA1(J)=XA(J)*CS-YA(J)*SN+X1 000613
10 YA1(J)=XA(J)*SN+YA(J)*CS+X2 000614
C 000615
C JACOBIAN OF THE TRANSFORMATION 000616
C 000617
DX1=1. 000618
DX2=0. 000619
DY1=0. 000620
DY2=1. 000621
DO 20 I=1, M 000622
J=NRF(I) 000623
DX3(J)=-XA(J)*SN-YA(J)*CS 000624
20 DY3(J)=XA(J)*CS-YA(J)*SN 000625
C 000626
C FUNCTIONS AND DERIVATIVES 000627
C 000628
IF(N.EQ.3)GO TO 40 000629
DO 30 I=4, N 000630
DO 30 J=1, M 000631
30 DF(J, I)=0.0 000632
40 DO 50 I=1, M 000633
J=NRF(I) 000634
K=KTC(J) 000635
IR=KOC(J) 000636
NZ= IABS(MD(J)) 000637
XA1P=XA1(J) 000638
YA1P=YA1(J) 000639
T1P=T1(J) 000640
T2P=T2(J) 000641
T3P=T3(J) 000642
T4P=T4(J) 000643
IF(K.EQ.0)GO TO 100 000644
IF(K.EQ.12)GO TO 120 000645
IF(IR.EQ.0)GO TO 131 000646
T5P=XP(IR) 000647
T6P=YP(IR) 000648
GO TO 132 000649
131 T5P=0. 000650

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T6P=0.
132 IF(K.EQ.13)GO TO 130
IF(K.EQ.23)GO TO 230
C
C     PARAMETERS FOR TOLCIR
C
100 IF(MD(J).EQ.0)GO TO 110
IF(MD(J).LT.0)GO TO 105
XA1P=X(NZ)
YA1P=X(NZ+1)
GO TO 110
105 T1P=T10(J)+X(NZ)
T2P=T20(J)+X(NZ+1)
110 CALL TOLCIR(XA1P,YA1P,T1P,T2P,T3P,FF,D1,D2,D3,D4)
GO TO 60
C
C     PARAMETERS FOR TOLXY
C
120 IF(MD(J).EQ.0)GO TO 125
IF(MD(J).LT.0)GO TO 122
XA1P=X(NZ)
YA1P=X(NZ+1)
GO TO 125
122 T1P=T10(J)+X(NZ)
T2P=T20(J)+X(NZ)
T3P=T30(J)+X(NZ+1)
T4P=T40(J)+X(NZ+1)
125 CALL TOLXY(XA1P,YA1P,T1P,T2P,T3P,T4P,FF,D1,D2,D3,D4)
GO TO 60
C
C     PARAMETERS FOR TOLXR
C
130 IF(MD(J).EQ.0)GO TO 135
IF(MD(J).LT.0)GO TO 133
XA1P=X(NZ)
YA1P=X(NZ+1)
GO TO 135
133 T1P=T10(J)+X(NZ)
T2P=T20(J)+X(NZ)
T5P=X(NZ)
T6P=X(NZ+1)
135 CALL TOLXR(XA1P,YA1P,T1P,T2P,T3P,T4P,T5P,T6P,FF,D1,D2,D3,D4)
GO TO 60
C
C     PARAMETERS FOR TOLYR
C
230 IF(MD(J).EQ.0)GO TO 235
IF(MD(J).LT.0)GO TO 233
XA1P=X(NZ)
YA1P=X(NZ+1)
GO TO 235
233 T1P=T10(J)+X(NZ+1)
T2P=T20(J)+X(NZ+1)
T5P=X(NZ)
T6P=X(NZ+1)
235 CALL TOLYR(XA1P,YA1P,T1P,T2P,T3P,T4P,T5P,T6P,FF,D1,D2,D3,D4)
C
C     FINAL DERIVATIVES
C
60 DF(I,1)=D1*DX1+D2*DY1
DF(I,2)=D1*DX2+D2*DY2
DF(I,3)=D1*DX3(J)+D2*DY3(J)
F(I)=FF
IF(N.EQ.3)GO TO 50
IF(MD(J).EQ.0)GO TO 50

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C	T2P	- XMAX DIMENSION OF RECTANGULAR TOLERANCE REGION	000781
C	T3P	- YMIN DIMENSION OF RECTANGULAR TOLERANCE REGION	000782
C	T4P	- YMAX DIMENSION OF RECTANGULAR TOLERANCE REGION	000783
C	F	- RESIDUAL FUNCTION VALUE	000784
C	D1	- PARTIAL DERIVATIVE OF F W.R.T. X COORDINATE	000785
C	D2	- PARTIAL DERIVATIVE OF F W.R.T. Y COORDINATE	000786
C	D3	- PARTIAL DERIVATIVE OF F W.R.T. ADDITIONAL VARIABLE (COORDINATE X OF A REFERENCE POINT)	000787
C	D4	- PARTIAL DERIVATIVE OF F W.R.T. ADDITIONAL VARIABLE (COORDINATE Y OF A REFERENCE POINT)	000788
C			000789
C			000790
C			000791
	E1=T1P-XA1P		000792
	E2=XA1P-T2P		000793
	E3=T3P-YA1P		000794
	E4=YA1P-T4P		000795
	F=AMAX1(E1,E2,E3,E4)		000796
	IF(F.EQ.E1)GO TO 10		000797
	IF(F.EQ.E2)GO TO 20		000798
	IF(F.EQ.E3)GO TO 30		000799
	IF(F.EQ.E4)GO TO 40		000800
10	D1=-1.		000801
	D2=0.		000802
	D3=1.		000803
	D4=0.		000804
	GO TO 50		000805
20	D1=1.		000806
	D2=0.		000807
	D3=-1.		000808
	D4=0.		000809
	GO TO 50		000810
30	D1=0.		000811
	D2=-1.		000812
	D3=0.		000813
	D4=1.		000814
	GO TO 50		000815
40	D1=0.		000816
	D2=1.		000817
	D3=0.		000818
	D4=-1.		000819
50	RETURN		000820
	END		000821
C			000822
C			000823
	SUBROUTINE TOLXR(XA1P, YA1P, T1P, T2P, T3P, T4P, T5P, T6P, F, D1, D2, D3, D4)		000824
C			000825
C	THIS SUBROUTINE CALCULATES ERROR FUNCTION AND ITS DERIVATIVES		000826
C	FOR X-R TOLERANCE REGION.		000827
C			000828
C	XA1P - TRANSFORMED ACTUAL X COORDINATE OF A POINT OR		000829
C	ADDITIONAL VARIABLE IF IT IS A REFERENCE POINT		000830
C	AND CANDIDATE FOR DELETING		000831
C	YA1P - TRANSFORMED ACTUAL Y COORDINATE OF A POINT OR		000832
C	ADDITIONAL VARIABLE IF IT IS A REFERENCE POINT		000833
C	AND CANDIDATE FOR DELETING		000834
C	T1P - XMIN DIMENSION OF X-R TOLERANCE REGION		000835
C	T2P - XMAX DIMENSION OF X-R TOLERANCE REGION		000836
C	T3P - RMIN DIMENSION OF X-R TOLERANCE REGION		000837
C	T4P - RMAX DIMENSION OF X-R TOLERANCE REGION		000838
C	T5P - X COORDINATE OF A REFERENCE POINT		000839
C	T6P - Y COORDINATE OF A REFERENCE POINT		000840
C	F - RESIDUAL FUNCTION VALUE		000841
C	D1 - PARTIAL DERIVATIVE OF F W.R.T. X COORDINATE		000842
C	D2 - PARTIAL DERIVATIVE OF F W.R.T. Y COORDINATE		000843
C	D3 - PARTIAL DERIVATIVE OF F W.R.T. ADDITIONAL VARIABLE		000844
C	(COORDINATE X OF A REFERENCE POINT)		000845

A=XA1P-T5P	000911
B=YA1P-T6P	000912
D=SQRT(A*A+B*B)	000913
E3=T3P-D	000914
E4=D-T4P	000915
F=AMAX1(E1,E2,E3,E4)	000916
IF(F.EQ.E1)GO TO 10	000917
IF(F.EQ.E2)GO TO 20	000918
IF(F.EQ.E3)GO TO 30	000919
IF(F.EQ.E4)GO TO 40	000920
10 D1=0.	000921
D2=-1.	000922
D3=0.	000923
D4=1.	000924
GO TO 50	000925
20 D1=0.	000926
D2=1.	000927
D3=0.	000928
D4=-1.	000929
GO TO 50	000930
30 D1=-A/D	000931
D2=-B/D	000932
D3=-D1	000933
D4=-D2	000934
GO TO 50	000935
40 D1=A/D	000936
D2=B/D	000937
D3=-D1	000938
D4=-D2	000939
50 RETURN	000940
END	000941