SPACE MAPPING BASED DEVICE MODELING AND CIRCUIT OPTIMIZATION

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Abstract

Electromagnetics (EM) based device modeling and circuit optimization through Space Mapping (SM) technologies are reviewed. The SM concept continues to promise important benefits in the next generation of design optimization methodologies. Artificial Neural Networks can be incorporated into the SM optimization strategies. Aggressive Space Mapping (ASM) optimization closely follows the traditional experience and intuition of designers, while being rigorously grounded mathematically. Current progress in the development of suitable algorithms and software engines are presented. The SM concept addresses the contradictory challenge of exploitation of device models for CAD that are both accurate and fast.



Outline

a comprehensive Generalized Space Mapping (GSM) tableau approach (*Bandler et al., 1999*) to engineering device modeling exploiting Frequency Space Mapping (FSM) (*Bandler et al., 1995*) and the Multiple Space Mapping (MSM) (*Bandler et al., 1998*) is reviewed

a Neural Space Mapping (NSM) optimization approach exploiting our SM-based neuromodeling techniques is presented (*Bakr et al., 2000*)

new work on Space Mapping optimization exploiting surrogate models is described (Bakr et al., 2000)

a state-of-the-art engineering optimization system including the latest Space Mapping technology, the SMX system, is described (*Bandler et al., 2000*)



Multiple Space Mapping (MSM) Concept

MSM for Frequency Intervals (MSMFI)





Mathematical Formulation for GSM

(Bandler et al., 1999)

the *k*th mapping targeting the sub-response or the response R in the *k*th frequency sub-range is given by

$$(\boldsymbol{x}_{ck}, \boldsymbol{\omega}_{ck}) = \boldsymbol{P}_k(\boldsymbol{x}_f, \boldsymbol{\omega})$$

or, in matrix form, assuming a linear mapping

$$\begin{bmatrix} \boldsymbol{x}_{ck} \\ \boldsymbol{\omega}_{ck} \end{bmatrix} = \begin{bmatrix} \boldsymbol{c}_{k} \\ \boldsymbol{\delta}_{k} \end{bmatrix} + \begin{bmatrix} \boldsymbol{B}_{k} & \boldsymbol{s}_{k} \\ \boldsymbol{t}_{k}^{T} & \boldsymbol{\sigma}_{k} \end{bmatrix} \begin{bmatrix} \boldsymbol{x}_{f} \\ \boldsymbol{\omega} \end{bmatrix}$$

the mapping parameters $\{c_k, B_k, s_k, t_k, \sigma_k, \delta_k\}$ can be evaluated, directly or indirectly, by solving the optimization problem

$$\min_{\boldsymbol{c}_k, \, \boldsymbol{B}_k, \, \boldsymbol{s}_k, \, \boldsymbol{t}_k, \, \sigma_k, \, \delta_k} \left\| \begin{bmatrix} \boldsymbol{e}_{k1}^T & \boldsymbol{e}_{k2}^T & \cdots & \boldsymbol{e}_{km}^T \end{bmatrix}^T \right\|$$

where *m* is the number of base points selected in the fine model space and e_{kj} is an error vector given by

$$e_{kj} = \mathbf{R}_f(\mathbf{x}_f^{(j)}, \omega) - \mathbf{R}_c(\mathbf{x}_{ck}^{(j)}, \omega_{ck}), \quad j = 1, 2, ..., m$$



the fine and coarse models





the region of interest

 $15 \text{ mil} \le H \le 25 \text{ mil}$ $5 \text{ mil} \le X \le 15 \text{ mil}$ $5 \text{ mil} \le Y \le 15 \text{ mil}$ $8 \le \varepsilon_r \le 10$

the frequency range is 2 GHz to 20 GHz with a step of 2 GHz

the number of base points is 9 and the number of test points is 50

the width W of the input lines is determined in terms of H and so that the characteristic impedance of the input lines is 50 ohm

the width W_1 is taken as 1/3 of the width W

the width W_2 is obtained so that the characteristic impedance of the microstrip line after the step connected to port 2 is twice that of the microstrip line after the step connected to port 1



MSM for Frequency Intervals (MSMFI) was developed to enhance the accuracy of the T-Junction coarse model

the total frequency range was divided into two intervals: 2-16 GHz and 16-20 GHz

he mapping parameters are		2 GHz to 16 GHz	16 GHz to 20 GHz		
	В	$\begin{bmatrix} 1.04 & 0.07 & 0.01 & 0.08 & -0.06 & 0.00 & 0.22 \\ 0.00 & 0.89 & 0.00 & -0.07 & -0.20 & 0.06 & -0.03 \\ -0.00 & 0.07 & 0.99 & 0.04 & -0.12 & 0.01 & -0.06 \\ -0.04 & 0.00 & -0.01 & 0.97 & 0.10 & -0.06 & -0.27 \\ 0.01 & 0.04 & 0.00 & 0.03 & 0.99 & -0.05 & -0.03 \\ -0.13 & -0.05 & -0.04 & -0.16 & 0.12 & 0.99 & 0.62 \\ -0.08 & 0.12 & -0.03 & 0.00 & -0.07 & 0.03 & 0.83 \end{bmatrix}$	$\begin{bmatrix} 0.99 & 0.02 - 0.00 & 0.01 - 0.09 - 0.01 & 0.13 \\ 0.05 & 0.85 & 0.01 - 0.07 - 0.28 & 0.01 - 0.01 \\ -0.06 & 0.15 & 0.98 & 0.04 - 0.25 & 0.00 & 0.02 \\ -0.10 - 0.06 - 0.03 & 0.88 & 0.13 - 0.09 - 0.27 \\ 0.08 & 0.04 & 0.03 & 0.11 & 1.07 - 0.04 - 0.12 \\ -0.14 - 0.02 - 0.05 - 0.15 & 0.23 & 1.03 & 0.51 \\ -0.13 & 0.22 - 0.04 & 0.02 - 0.07 & 0.03 & 0.87 \end{bmatrix}$		
	С	$\begin{bmatrix} 0.02 & 0.01 & -0.01 & -0.03 & -0.01 & 0.07 & -0.03 \end{bmatrix}^T$	$\begin{bmatrix} 0.01 & 0.01 & -0.01 & -0.03 & -0.01 & 0.05 & -0.03 \end{bmatrix}^T$		
	S	$\begin{bmatrix} -0.01 & 0.09 & -0.10 & -0.02 & 0.00 & -0.02 & -0.20 \end{bmatrix}^T$	$\begin{bmatrix} 0.00 & 0.01 & -0.01 & 0.00 & 0.00 & 0.00 & -0.02 \end{bmatrix}^T$		
	t	0	$\begin{bmatrix} 0.01 & 0.00 & -0.02 & 0.00 & 0.00 & 0.00 \end{bmatrix}^T$		
	σ	0.851	0.957		
	δ	-0.003	0.008		



the responses of the shaped T-Junction at two test points in the region of interest by Sonnet's em (•), by the coarse model (---) and by the enhanced coarse model (---)





the enhanced coarse model for the shaped T-Junction can be utilized in optimization

the optimization variables are X and Y

the other parameters are kept fixed (W = 24 mil, H = 25 mil and $\varepsilon_r = 9.9$)

the design specifications are

$$|S_{11}| \le 1/3, |S_{22}| \le 1/3$$

in the frequency range 2 GHz to 16 GHz

the minimax optimizer in OSA90/hope reached the solution

X = 2.1 mil and Y = 21.1 mil



responses of the optimal shaped T-Junction by Sonnet's em (•), by the coarse model (---) and by the enhanced coarse model (—)





Neural Space Mapping (NSM) Optimization

(Bakr et al., 2000)

exploits the SM-based neuromodeling techniques (Bandler et al., 1999)

coarse models are used as sources of knowledge that reduce the amount of learning data and improve the generalization and extrapolation performance

NSM requires a reduced set of upfront learning base points

the initial learning base points are selected through sensitivity analysis using the coarse model

neuromappings are developed iteratively: their generalization performance is controlled by gradually increasing their complexity starting with a 3-layer perceptron with 0 hidden neurons



Neural Space Mapping (NSM) Optimization Concept

step 1





(2n + 1 learning base points for a microwave circuit with n design parameters)



Neural Space Mapping (NSM) Optimization Concept (continued)

step 3

step 4





Neural Space Mapping (NSM) Optimization Algorithm Start COARSE OPTIMIZATION: find the optimal coarse model solution x_c^* that generates the desired response R^* $\boldsymbol{R}_{c}(\boldsymbol{x}_{c}^{*}) = \boldsymbol{R}^{*}$ Form a learning set with $B_p = 2n+1$ base points, by selecting 2n additional points around \boldsymbol{x}_{c}^{*} , following a star distribution Choose the coarse optimal solution as a starting point for the fine model $x_{f} = x_{c}^{*}$ Include the new x_f in the learning Update \boldsymbol{x}_{f} set and increase B_n by one Calculate the fine response $\boldsymbol{R}_{f}(\boldsymbol{x}_{f})$ SM BASED NEUROMODELING: Find the simplest neuromapping PSMBNM OPTIMIZATION: such that Find the optimal x_f such that no $\boldsymbol{R}_f(\boldsymbol{x}_f) \approx \boldsymbol{R}^*$ End ves $\boldsymbol{R}_{f}(\boldsymbol{x}_{f}^{(l)}, \omega_{j}) \approx \boldsymbol{R}_{c}(\boldsymbol{P}(\boldsymbol{x}_{f}^{(l)}, \omega_{j}))$ $\boldsymbol{R}_{SMBN}(\boldsymbol{x}_{f}) = \boldsymbol{R}_{c}(\boldsymbol{P}(\boldsymbol{x}_{f})) \approx \boldsymbol{R}^{*}$ $l = 1, ..., B_p$ and $j = 1, ..., F_p$



HTS Quarter-Wave Parallel Coupled-Line Microstrip Filter

(Westinghouse, 1993)



we take $L_0 = 50$ mil, H = 20 mil, W = 7 mil, $\varepsilon_r = 23.425$, loss tangent = 3×10^{-5} ; the metalization is considered lossless

the design parameters are $\mathbf{x}_f = [L_1 \ L_2 \ L_3 \ S_1 \ S_2 \ S_3]^T$



NSM Optimization of the HTS Microstrip Filter

specifications

$$\begin{split} |S_{21}| &\geq 0.95 \text{ for } 4.008 \text{ GHz} \leq f \leq 4.058 \text{ GHz} \\ |S_{21}| &\leq 0.05 \text{ for } f \leq 3.967 \text{ GHz and } f \geq 4.099 \text{ GHz} \end{split}$$

"fine" model: Sonnet's *em*TM with high resolution grid

"coarse" model: OSA90/hope™ built-in models of open circuits, microstrip lines and coupled microstrip lines





NSM Optimization of the HTS Filter (continued)

coarse and fine model responses at the optimal coarse solution

 $\mathbf{x}_{c}^{*} = [188.33 \ 197.98 \ 188.58 \ 21.97 \ 99.12 \ 111.67]^{T}$ (mils)

OSA90/hopeTM (-) and em^{TM} (•)





NSM Optimization of the HTS Filter (continued)

 $em^{TM}(\bullet)$ and FPSM 7-5-3 (–) model responses at the NSM solution using a fine frequency sweep





Space Mapping Optimization Exploiting Surrogates (*Bakr et al.*, 2000)

a powerful new Space Mapping (SM) optimization algorithm has been developed

it draws upon recent developments in both surrogate model-based optimization and modeling of microwave devices

SM optimization is formulated as a general optimization problem of a surrogate model

this model is a convex combination of a mapped coarse model and a linearized fine model

it exploits, in a novel way, a linear frequency-sensitive mapping

during the optimization iterates, the coarse and fine models are simulated at different sets of frequencies.

this approach is shown to be especially powerful if a significant response shift exists



The Surrogate Model

our surrogate model is a convex combination of a mapped coarse model and a linearized fine model

the *i*th iteration surrogate model is

$$\boldsymbol{R}_{s}^{(i)}(\boldsymbol{x}_{f}) = \lambda^{(i)} \boldsymbol{R}_{m}^{(i)}(\boldsymbol{x}_{f}) + (1 - \lambda^{(i)})(\boldsymbol{R}_{f}(\boldsymbol{x}_{f}^{(i)}) + \boldsymbol{J}_{f}^{(i)} \Delta \boldsymbol{x}_{f}), \quad \lambda^{(i)} \in [0, 1]$$

the mapped coarse model utilizes the frequency-sensitive mapping

$$\boldsymbol{R}_{f}(\boldsymbol{x}_{f},\omega_{j}) \approx \boldsymbol{R}_{m}^{(i)}(\boldsymbol{x}_{f},\omega_{j}) = \boldsymbol{R}_{c}(\boldsymbol{P}^{(i)}(\boldsymbol{x}_{f},\omega_{j}),\boldsymbol{P}_{\omega}^{(i)}(\boldsymbol{x}_{f},\omega_{j}))$$

where

$$\begin{bmatrix} \mathbf{P}^{(i)}(\mathbf{x}_f, \omega_j) \\ \mathbf{P}^{(i)}_{\omega}(\mathbf{x}_f, \omega_j) \end{bmatrix} = \begin{bmatrix} \mathbf{B}^{(i)} & \mathbf{s}^{(i)} \\ \mathbf{t}^{(i)T} & \sigma^{(i)} \end{bmatrix} \begin{bmatrix} \Delta \mathbf{x}_f \\ \omega_j \end{bmatrix} + \begin{bmatrix} \mathbf{c}^{(i)} \\ \gamma^{(i)} \end{bmatrix}$$

the parameters $B^{(i)} \in \Re^{n \times n}$, $s^{(i)} \in \Re^{n \times 1}$, $t^{(i)} \in \Re^{n \times 1}$, $c^{(i)} \in \Re^{n \times 1}$, $\sigma^{(i)} \in \Re^{1 \times 1}$ and $\gamma^{(i)} \in \Re^{1 \times 1}$ are obtained such that the mapped coarse model approximates the fine model over a given set of fine model points $V^{(i)}$ and frequencies ω



The Surrogate Model (continued)

the mapping parameters are obtained through the optimization process

$$[\boldsymbol{B}^{(i)}, \boldsymbol{s}^{(i)}, \boldsymbol{t}^{(i)}, \boldsymbol{\sigma}^{(i)}, \boldsymbol{c}^{(i)}, \boldsymbol{\gamma}^{(i)}] = \arg\left\{\min_{\boldsymbol{B}, \boldsymbol{s}, \boldsymbol{t}, \boldsymbol{\sigma}, \boldsymbol{c}, \boldsymbol{\gamma}} \left\| \begin{bmatrix} \boldsymbol{e}_{1}^{T} & \boldsymbol{e}_{2}^{T} & \cdots & \boldsymbol{e}_{N_{p}}^{T} \end{bmatrix}^{T} \right\|\right\}$$

where

$$\boldsymbol{e}_{k} = \boldsymbol{R}_{m}^{(i)}(\boldsymbol{x}_{f}^{(k)}) - \boldsymbol{R}_{f}(\boldsymbol{x}_{f}^{(k)}) \qquad \forall \, \boldsymbol{x}_{f}^{(k)} \in \boldsymbol{V}^{(i)}$$



The Algorithm Flowchart





The SMX System (Bandler et al., 2000)

SMX is a new generation engineering optimization system

currently it provides the following optimization capabilities minimax Huber Space Mapping using Surrogate Models (*Bakr et al., 2000*)

currently it can be interfaced to OSA90 user supplied executable programs



Object Oriented SMX System Design: Data Flow Between Modules





Object Oriented SMX System Design (continued)

optimizer object: general optimizers





Object Oriented SMX System Design (continued)

simulator object: interface to simulators





Object Oriented SMX System Design (continued)

model object: enhanced wrapper of simulators





SMX Example: A Two-section 10:1 Capacitively-loaded Impedance Transformer Design

fine model



coarse model



specifications

 $|S_{11}| \le 0.50$ for $0.5 \text{ GHz} \le \omega \le 1.5 \text{ GHz}$



Object Oriented SMX System Example: Problem Setup Wizard

step 1: project setup

SMX Project Setup		×
Project Location		
Project Name:	Project 1	
Location:	C:\shasha\CPP\SMX_PROJEC	2
Simulator		
Model A:	OSA90	•
Model B:	OSA90	•
- Simulator Files		
Model A Filename:	Fine_model.ckt	F
Model B Filename:	Coarse_model.ckt	2
		Cancel Next >>



Object Oriented SMX System Example: Problem Setup Wizard

step 2: responses and specifications

SMX	Responses	& Specifica	tions				×
S S	pecification S Start 0.5	etup Stop 1.5	Step	Response ms11 _		Value	Add
_ S	pecifications-						
	Start 0.500000	Stop 1.500000	Step 0.100000	Response ms11	Constraint <=	Value 0.500000	Delete
	1apping Param	ieters		Simulatio	on Setup		
	Designable	e Parameters			Number of I	terations: 10	
C Space				Number of Ports: 1			
	C Space and Frequency (decoupled)						
	C Space and	d Frequency (c	oupled)		Cancel	<< Back	Next >>



Object Oriented SMX System Example: Problem Setup Wizard

step 3: parameter setup

MX Parameter Set Parameter Setup Parameter Name	up :		- I En I En	able Parameter able Discrete F	for Optimization Perturbation
Initial Value Minimum Value Maximum Value Step 1 0.0001 1000 1e-005 Add					
Parameter L1 L2	Initial 0.700000 0.650000	Minimum 0.000100 0.000100	Maximum 1000.000 1000.000	Step 0.000010 0.000010	Enabled Yes Yes
,		[<u>C</u> ancel	<< Back	Delete



Object Oriented SMX System Example: Initial and Optimal Coarse Model Responses



Object Oriented SMX System Example: Initial and Optimal Fine Model Responses





Object Oriented SMX System Example: Objective Function Value





🕑 SMX - SMX1	
<u>File E</u> dit <u>V</u> iew <u>W</u> indow <u>H</u> elp <u>S</u> ettings <u>W</u> izard <u>O</u> ptimize <u>P</u> lot	
🗅 😅 🖬 👗 🖶 💼 🥵 🦿 🚥	
SMX Project Setup Project Location Project Name: Project 1 Location: C:\shasha\CPP\SMX_PROJEC Simulator Model A: OSA90 Model B: OSA90 Simulator Files Model A Filename: Fine_model.ckt	SMX Plotter X 2.5 0K 1.9 0K 1.3 0K 0.8 0K 0.8 0K 0.1 0K 0.8 0K 0.1 0K 0.8 0K 0.1 0K 0.2 0K 0.3 0K 0.4 0K 0.7 1.3 0.8 0K 0.1 0K 0.2 0K 0.3 0K 0.4 0K 0.7 1.3 0.8 0K 0.9 0K 0.1 0K 0K 0K <
Model B Filename: Coarse_model.ckt	ameter for Optimization crete Perturbation
Specification Setup Designable Parameters List Start Stop Step Response Value 0.5 1.5 0.1 ms11 <=	5.0 4.2 5.0 5.0 5.0 4.2 5.0 7 Tick 7 Tick 6 I 9 7 Tick 6 I 9 7 Tick 5 I 9 7 Tick 5 I 9 7 Tick 5 I 9 7 Tick 5 I 9 7 Tick
Mapping Parameters Cancel	2.5 1.6 0.8 0.5 0.7 0.8 1.0 1.2 1.3 1.5 Legend ms11 Legend ms11



Conclusions

we review Generalized Space Mapping (GSM) as a new engineering device modeling framework that exploits Frequency Space Mapping (FSM) and Multiple Space Mapping (MSM)

we review an innovative algorithm for EM optimization based on Space Mapping technology and Artificial Neural Networks

Neural Space Mapping (NSM) optimization exploits our SM-based neuromodeling techniques

a novel SM optimization algorithm based on surrogate models is presented

the surrogate model is a convex combination of a mapped coarse model and a linearized fine model

the state-of-the-art SMX engineering optimization system including Space Mapping technology is briefly reviewed



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